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**Technical Report 851** 

# A PROGRAM TO COMPUTE **VERTICAL ELECTRIC ELF FIELDS** IN A LATERALLY INHOMOGENEOUS **EARTH-IONOSPHERE WAVEGUIDE**



JA Ferguson **LR Hitney** and RA Pappert **Environmental Sciences Department** 

1 December 1982

Prepared for **Defense Nuclear Agency** 

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**NAVAL OCEAN SYSTEMS CENTER** San Diego, California 92152



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Technical Director

# **ADMINISTRATIVE INFORMATION**

This work was performed under program element 62715H, project 99QAXHB (NOSC 532-MP20) by members of the Propagation Modeling Branch and was accomplished from June 1982 to December 1982. This document was approved for publication 1 December 1982.

Released by JH Richter, Head EM Propagation Division Under authority of JD Hightower, Head Environmental Sciences Department SECURITY CLASSIFICATION OF THIS PAGE (When Date Entered)

REPORT DOCUMENTATION	PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER
NOSC Technical Report 851 (TR 851)	AD-PIR8805	
4. TITLE (and Subtitle)	W	5. TYPE OF REPORT & PERIOD COVERED
A PROGRAM TO COMPUTE VERTICAL ELEC	Interim	
ELF FIELDS IN A LATERALLY INHOMOGEN	June 1982 – December 1982	
EARTH-IONOSPHERE WAVEGUIDE		6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(a)		S. CONTRACT OR GRANT NUMBER(s)
JA Ferguson		
LR Hitney and	•	DNA MIPR 82-608
RA Pappert		·
9. PERFORMING ORGANIZATION NAME AND ADDRESS	,	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS
Naval Ocean Systems Center	,	62715H,'99QAXHB
San Diego, CA 92152		(NOSC 532-MP20)
11. CONTROLLING OFFICE NAME AND ADDRESS		12. REPORT DATE
Defense Nuclear Agency		1 December 1982
Washington, DC 20305		13. NUMBER OF PAGES
		62
14. MONITORING AGENCY NAME & ADDRESS(II differen	nt from Controlling Office)	15. SECURITY CLASS. (of this report)
		Unclassified
	!	15a. DECLASSIFICATION/DOWNGRADING
		SCHEDULE
Approved for public release; distribution unlimite	d.	
17. DISTRIBUTION STATEMENT (of the abstract entered	in Block 20, il different froz	m Report)
18. SUPPLEMENTARY NOTES		
19. KEY WORDS (Continue on reverse side if necessary as	id identify by block number)	
ELF radio; D-region, Sporadic-E		
Numerical predictions		
-		
20. ABSTRACT (Continue on reverse elde if necessary an	d identify by block number)	
A computer program for calculating ELF guide is presented. The program is based on a sime equation which is solved using a moment method, guide disturbance must effectively vanish outside for modeling rectangular, circular, and elliptical difference dipole is calculated. Waveguide height effective dipole is calculated.	ple surface propagation n The disturbance must be a rectangle of several meg aturbances. The lateral p ects are allowed for withi	model formulated in terms of an integral e localized to the extent that the wave- gameters on a side. The program allows propagation function for the vertical
The total vertical electric field is also calculated.	4-7	

DD 1 JAN 73 1473 EDITION OF I NOV 65 IS OBSOLET S/N 0102- LF- 014- 6601

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S/N 0102- LF- 014- 6601

UNCLASSIFIED

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#### I. INTRODUCTION

Since an ELF signal from a remote transmitter is received over a range of azimuth angles, lateral ionospheric gradients produced by sporadic E layering or nuclear depressions can produce significant effects on propagation in the This is because the Fresnel zone size can be large as lower ELF band. compared with the distance over which the ionosphere changes significantly in the lateral direction. Although a number of workers have addressed the question of off-path effects (Wait<sup>1</sup>, Galejs<sup>2</sup>, Greifinger and Greifinger<sup>3</sup>, Field 4,5, Field and Joiner 6,7, Pappert 8) no formulation exists which can fully account for the propagation effects produced by a localized disturbance with simultaneous allowance for vertical inhomogeneity, lateral inhomogeneity, and anisotropy in a spherical geometry. It has been common practice to estimate the effects of lateral gradients by using a simple surface propagation model introduced by Wait and more fully developed by the Greifingers and Field. The formulation reduces the problem to an integral equation description of propagation along the earth's surface. The theory is predicated on the palatable assumption that the field can be separated into lateral and height dependent functions when the lateral ionspheric gradients are considerably smaller than the vertical gradients. When applying the method to nocturnal environments additional assumptions are made. Among these is the omission of nonreciprocal effects. This is well justified in the ambient case as well as for daytime and depressed ionospheres. However, it is known that under sporadic E layering considerable mixing between TE and TM wave can occur<sup>10</sup>. Thus, when the surface propagation model is applied to sporadic E environments the scattered TE component is neglected. The validity conditions for the formulation are probably best satisfied under conditions of either natural or man-made depressed ionospheres.

The purpose of this report is to document a computer program, based on the surface propagation model, which is useful to the user community for estimating the effects of localized ionospheric disturbances on propagation of the vertical electric field component E, at lower ELF frequencies. A moments method 11 serves as the basis for the solution of the integral equation. Though the method is powerful, in the present program, practical storage requirements restrict application to disturbances which effectively vanish outside a rectangle of several megameters on one side. It is hoped that limitation will be relaxed in future work. The program allows in some measure, for modeling of rectangular, circular, and elliptical disturbance The lateral propagation function, W, defined as the ratio of the shapes. disturbed laterally dependent part of the vertical field component,  $E_z$ , to the undisturbed field component is calculated as is the absolute value of the total  $\mathbf{E}_{\mathbf{z}}$  field component in the disturbed guide. The latter calculation allows in approximate manner for guide height effects via WKB formalism as applied to waveguide propagation.

The program requires eigenangle inputs for both the ambient and disturbed regions of the guide as well as end-on horizontal dipole excitation factors for the vertical  $\mathbf{E}_{\mathbf{Z}}$  field component. These must be supplied from a waveguide program such as that of reference 12.

# II. SUMMARY OF EQUATIONS

Subject to the assumption that the vertical,  $\mathbf{E}_{\mathbf{z}}$ , field component can be separated into lateral and height dependent functions, the lateral dependence  $\psi(\mathbf{x},\mathbf{y})$  is given by <sup>5</sup>

$$\psi(x,y) = \psi^{i}(x,y) - \frac{ik^{2}}{4} \int_{-\infty}^{\infty} dx' dy' \left(s^{2}(x',y') - s_{0}^{2}\right) G(|r-r'|) \psi(x',y')$$
 (1)

where S is the sine of the eigenangle for the disturbed guide,  $S_0$  the sine for the unperturbed guide, k the free space wave number, and the superscript i signifies the unperturbed incident field. The Green's function G(|r-r'|) is given by

$$G(|\vec{r} - \vec{r}'|) = \begin{cases} \frac{|\vec{r} - \vec{r}'|}{|\vec{r} - \vec{r}'|} & H_0^{(2)}\{ks_0|\vec{r} - \vec{r}'|\} \\ = e^{\sin(\frac{|\vec{r} - \vec{r}'|}{a_e})} \end{cases}$$
(2)

where

$$\dot{r} = x\dot{i} + y\dot{j} \quad \text{and} \quad \dot{r}' = x'\dot{i} + y'\dot{j}. \tag{3}$$

Here  $a_e$  is the earth's radius and the x, y, z are the Cartesian coordinates. z is measured vertically upwards into the ionosphere and x is measured horizontally with x-z the plane of incidence. Unit vectors in the x and y directions are denoted by  $\frac{1}{1}$  and  $\frac{1}{2}$ . The square root factor in equation (2) has been introduced to allow for the geometric spreading appropriate to a spherical geometry. Beyond that, x, y and x', y' are taken to be rectangular coordinates in a flat earth geometry. The quantity  $H_D^{(2)}$  is the Hankel

coordinates in a flat earth geometry. The quantity  $H_p^{(2)}$  is the Hankel function of order p of the second kind. The unperturbed lateral dependent function,  $\Psi^i$ , is taken to be appropriate for the vertical electric field,  $E_z$ , launched by the end-on component of a ground based horizontal electric dipole source oriented in the x direction and given by

$$\psi^{i} = B \sqrt{\frac{|\vec{r}|}{a_{e} \sin(\frac{|\vec{r}|}{a_{e}})}} H_{1}^{(2)} \{ks_{0}|\vec{r}|\} \frac{x}{|\vec{r}|}$$
(4)

where B is a constant. Again the square root factor allows for the spreading appropriate to a spherical geometry. The discrete analog of equation (1) for field points within the disturbed region consists of the N  $\times$  N system of linear equations:

$$\sum_{n=1}^{N} A_{mn} \psi_{n} = \psi_{m}^{i} ; m = 1, 2, ..., N$$
 (5)

Allowance is made for modeling rectangular, circular, and elliptical disturbances by subdividing them into square mesh cells. It is common practice in such circumstances to simplify the integrations involving cylindrical functions by approximating each square cell by a circle of equal area. It is also common practice to take the electric field to be constant over the area of a cell. However, larger cells can be tolerated if the electric field is allowed to vary over the area of a cell. At least two methods of allowing for this variation have been described in the literature 13. In this work the method called 'plane wave correction' is used. The method assumes isotropic propagation within and between each cell and that should be a reasonable approximation in the present problem since anisotropy of propagation at ELF

frequencies is quite small. Translated into the notation of this work, the results of reference 13 yield for the A-matrix elements:

$$A_{mm} = 1 + \left(\frac{s_{m}^{2}}{s_{0}^{2}} - 1\right) \left[\left(\frac{s_{m}^{2}}{s_{0}^{2}} + 1\right) + \frac{i\pi}{2} k s_{0} a \left(1 - \frac{1}{4} \left(k s_{m} a\right)^{2}\right) H_{1}^{(2)}(k s_{0} a) + \frac{i\pi}{4} \left(k s_{m} a\right)^{2} H_{2}^{(2)}(k s_{0} a)\right]$$

$$(6)$$

$$A_{mn} = \frac{i\pi k S_0 a}{2} \left( \frac{S_n^2}{S_0^2} - 1 \right) G(|r_m^+ - r_n^+|) \left[ \left( 1 - \frac{1}{4} (k S_n a)^2 \right) J_1(k S_0 a) + \frac{1}{2} \left( \frac{S_n^2}{S_0^2} \right) k S_0 a J_2(k S_0 a) \right]; m \neq n$$
(7)

The Green's function, G, is given by equation (2) with  $r_m$  replacing r and  $r_n$  replacing r. Also,  $J_p$  is the Bessel function of order p of the first kind. In terms of the  $\Psi_n$  determined by equation (5), and the  $A_{mn}$  given by equation (7), the field at a point,  $r_m$ , exterior to the disturbed region is given by:

$$\psi(r_{m}) = \psi^{i}(r_{m}) - \sum_{n=1}^{N} A_{mn} \psi_{n}$$
 (8)

Equations (5) through (8) are used in the present program to determine the dB value,

$$W = 20 \log_{10} \{ \psi(x,y) / \psi^{1}(x,y) \}, \tag{9}$$

of the disturbed lateral function relative to its undisturbed value.

Another output of the program makes allowance for dependence of the vertical electric field on height of the guide via the approximate WKB formalism. For a laterally homogeneous guide the  $\mathbf{E}_{\mathbf{Z}}$  field generated by the end-on component of a horizontal dipole may be expressed as

$$\mathbf{E}_{\mathbf{z}} \sim -iQ \frac{\mathbf{S}^{3/2}}{\frac{\partial \mathbf{F}}{\partial \theta}} \frac{\left(1 - \mathbf{I}^{\mathbf{R}} \mathbf{I} \mathbf{I}^{\mathbf{R}} \mathbf{I}\right)}{\sqrt{\mathbf{R}}_{\parallel}} \left(1 + \sqrt{\mathbf{R}}_{\parallel}\right) \left\{ \mathbf{C} \left(1 - \sqrt{\mathbf{R}}_{\parallel}\right) \right\} \Psi(\mathbf{x}, \mathbf{y}) \tag{10}$$

where F is the modal function and  $\partial F/\partial\theta$  its derivative evaluated at the eigenangle. S and C are the sine and cosine of the eigenangle.  $_{\perp}\bar{R}_{\perp}$  and  $_{\parallel}\bar{R}_{\parallel}$  are TE and TM Fresnel reflection coefficients referenced to the ground and  $_{\perp}R_{\perp}$  is the ionospheric TE reflection coefficient referenced to the ground. In the absence of anisotropy the quantity  $(1-_{\perp}R_{\perp\perp}\bar{R}_{\perp})$  would cancel an identical term occurring in the  $(\partial F/\partial\theta)$ . The Fresnel coefficient  $_{\parallel}\bar{R}_{\parallel}$  is

$$\bar{R}_{\parallel} = (N_{G}^{2} - \sqrt{N_{G}^{2} - s^{2}})/(N_{G}^{2} + \sqrt{N_{G}^{2} - s^{2}})$$
(11)

where  $N_G$  is the complex refractive index of the ground. Because the magnitude of  $N_G$  is much greater than unity in the lower ELF band good approximations are:

$$1 + \sqrt{R_{\parallel}} \approx 2$$
 and  $C(1 - \sqrt{R_{\parallel}}) \approx 2/N_{G}$  (12)

Thus, within the spirit of the WKB approximation the  $E_{_{\mathbf{Z}}}$  field becomes

$$E_{z} \approx -4Qi \left[ \frac{S^{3/2}}{\frac{\partial F}{\partial \theta}} \left( 1 - {}_{\perp}R_{\perp \perp} \tilde{R}_{\perp} \right) \right]_{r}^{1/2} \left[ \frac{S^{3/2}}{\frac{\partial F}{\partial \theta}} \left( 1 - {}_{\perp}R_{\perp \perp} \tilde{R}_{\perp} \right) \right]_{t}^{1/2} \frac{1}{N_{G}} \Psi(x,y) \tag{13}$$

where Q is a constant dependent upon dipole moment and frequency and the subscripts r and t stand for receiver and transmitter. That is, the first term in parenthesis is evaluated at the receiver while the second term in parenthesis and the factor  $N_G^{-1}$  are evaluated at the transmitter.

The factor B in equation (4) is taken to be

$$B = \sqrt{\frac{\pi k S_0 a_e}{2}} e^{-(3/4)\pi i}$$
 (14)

To express the vertical electric field,  $\mathbf{E}_{\mathbf{z}}$ , as given by equation (13) in microvolts/m, the factor Q has the value

$$Q = 2.849 \times 10^{-3} f_{kHz}^{3/2} (Id1)$$
 (15)

where  $f_{\rm kHz}$  is the frequency in kHz and Idl is the current moment in ampere meters.

# III. GEOMETRICAL MODELING OF THE DISTURBANCE

As described in the introduction, the program can be used to model square, rectangular, circular, and elliptical disturbances. In all cases the disturbance is defined to be symmetrical about both its x and y axes. The special case of a rectangular disturbance is required to be uniformly disturbed. Let  $x_0$  and  $y_0$  denote the coordinates of the center of the disturbance with respect to the location of the transmitter. Let  $L_x$  and  $L_y$  be the size of the disturbance along the x and y axis. The disturbance is overlaid by a grid which has  $n_x$  squares along the x axis and  $n_y$  squares along the y axis. The choice of  $L_x$ ,  $L_y$ ,  $n_x$ , and  $n_y$  must be such that  $L_x/n_x = L_y/n_y$ .

Since we assume that the disturbance is symmetrical about the x and y axis, we only need to specify the waveguide eigen solution parameters along the x axis. Let us denote these solutions by  $S_i$ . We take i=0 to denote the ambient or undisturbed values. The remaining  $S_i$  ( $S_1$  through  $S_N$ ) is assumed to be uniformly distributed along the x axis from  $x_0$  to  $x_0 + \frac{1}{2}L_x$ . Note that the value of  $n_x$  is not related to that of N. If N=1, then a uniform disturbance will be assumed. This is required for the rectangular disturbance. The remaining problem is to fill the disturbance grid with interpolated values of  $S_i$ .

Let us now consider a single subsquare within a square disturbance. Let the coordinates of the center of this subsquare be x and y. The smaller value of  $|x - x_0|$  and  $|y - y_0|$  is used to interpolate a value of S from the input list of  $S_i$ . This results in the disturbance grid being filled as illustrated in figure 1. In the figure the similarly shaded regions would all have the same value of S.

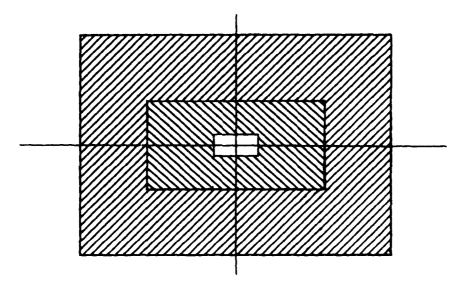


Figure 1. Diagram illustrating the distribution of S within a rectangular disturbance. The similarly shaded regions have the same value of S.

Let us consider an elliptical disturbance with an axial ratio  $R = L_y/L_x$ . The center of a given subsquare is at x and y. We can define an ellipse which is concentric with that of the outer edge of the disturbance. This ellipse intersects the x axis at a distance from  $x_0$  defined by

$$A = \left\{ (x - x_0)^2 + \left[ (y - y_0)/R \right]^2 \right\}^{1/2}$$
 (16)

The above expression can be used to calculate the value of A for each corner of the subsquare, say  $A_i$  where i=1,2,3 or 4. If the smallest of the  $A_i$  is greater than  $L_x$ , then the subsquare is entirely outside the disturbance and  $S_0$  is used in the grid at that subsquare. If the largest of the  $A_i$  is less than  $L_x$ , then the subsquare is entirely inside the disturbance and the value of S for that subsquare is interpolated from the input list of  $S_i$ . The remaining case is that of a subsquare on the edge of the disturbance. In this case the subsquare is subdivided into 16 smaller squares. Let the coordinates of the

center of each of these smaller squares be  $x_m$  and  $y_m$ . For each of these squares we calculate  $A_m$  using equation (16). The value of S for the subsquare is given by

$$S = \frac{nS_N - (16-n)S_0}{16}$$
 (17)

where n is the number of subsquares which are within the ellipse. A circular disturbance is treated the same way as an elliptical one with R=1.

#### IV. DESCRIPTION OF INPUT

All input to the sporadic-E program is given in a data deck on the standard input unit. A listing of sample input showing the data deck setup is shown in figure 2.

There are two parts to the input. This first part is read in by means of a FORTRAN NAMELIST input format. The first card of each set of input must contain '&DATUM' in columns 2-7. This is followed by at least one blank and then data items separated by commas. The data items have the following forms:

'variable name' = constant,

OL

'array name' = set of constants (all separated by commas).

The data list is terminated by '&END'. All cards must have a blank in column 1.

The second part of the input follows the NAMELIST. The first card for this part is an identification card. It contains up to 80 columns of alphanumeric information and is used to label the output plots. Following the identification card a series of punched cards (obtained from the programs described in reference 14 with NPUNCH = 1) is input for each mode.

The first card gives the values of R, FREQ, AZIM, CODIP, MAGFLD, SIGMA and EPSR. Next there are two cards per mode. The first of these contains the complex eigenangle at the ground and values for the complex quantities T1 and T2. The second card contains the eigenangle at the ground (duplicate input) and values for T3 and T4. The quantities T1, T2, T3, and T4 are defined in reference 14.

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1	
2 800-0016 6 M 000 Ct 7 000 301 4 0350 6 3 000	
2	
2 KG 2000K+6K KK91K1	
Figure 2. Sample data input for the computer program.	

The following variables and arrays may be specified in the NAMELIST input:

- DM dipole moment in ampere meters.
- DMIN the minimum range in kilometers at which fields are calculated, printed, and plotted for IFLAG = 2.
- DMAX the maximum range in kilometers at which fields are calculated, printed, and plotted for IFLAG = 2.
- DELD the increment, in kilometers at which fields are calculated, printed, and plotted for IFLAG = 2.
- YMAX the maximum off axis value, in kilometers, at which fields are calculated, printed, and plotted for IFLAG = 1.
- DELY the increment in kilometers, at which fields are calculated printed and plotted for IFLAG = 1.
- IGRID = 0 indicates that the disturbance is either square
   or rectangular.
   IGRID = 1 indicates that the disturbance is either circular or
   elliptical.
- X0,Y0 coordinates in kilometers at center of disturbance. Y0 is also the initial value at which fields are calculated, printed, and plotted for IFLAG = 1.
- NUMX, the disturbance is divided into NUMX grids in the x- direction NUMY and NUMY grids in the y-direction (these are  $n_y$ ,  $n_y$  in the text).
- SIZEX defines the physical size of the disturbance. It is SIZEX SIZEY kilometers by SIZEY kilometers.
- IPLOT = 0 no plots are generated. If IPLOT = 1 two plots are generated. For IFLAG=2 the first plot is WMAG(DB) vs X(KM), equation (9). The second plot consists of two curves: EZUMAG (DB), equations (13) and (4), is a solid curve and EZPMAG (DB), equations (13) and (8), is a dashed curve. For IFLAG=1 WMAG, EZUMAG, and EZPMAG are plotted with respect to y for a fixed value of x.

XLNG the length in inches for the x-axis and y-axis for the YLNG field plots. WMIN the minimum and maximum values, in dB, desired on y-axis for WMAX the WMAG plot. EMIN the minimum and maximum values in DB desired on y-axis for **EMAX** the EZREL plot. XYIC the units per tic mark along the x-axis and y-axis for YTIC both plots.

Initial values of the namelist variables are presented in table 1.

TABLE 1
Namelist variables and initial values.

NAME	INITIAL VALUE	UNITS
DM	6.75E6	Ampere meters
DMIN	25.0	Kilometers
DMAX	1000.0	Kilometers
DELD	25.0	Kilometers
YMAX	5000.0	Kilometers
DELY	25.0	Kilometers
IFLAG	2	
IGRID	0	
X0	0.0	Kilometers
Y0	0.0	Kilometers
NUM	0	
NUMY	0	
SIZEX	1000.0	Kilometers
SIZEY	1000.0	Kilometers
IPLOT	0	
XLNG	5.0	Inches
YLNG	6.0	Inches
WMIN	-6.0	Decibels
WMAX	2.0	Decibels
EMIN	<b>-</b> 60	Decibels
EMAX	2.0	Decibels
XTIC	200.0	Kilometers
YTIC	0.2	Decibels

# V. DESCRIPTION OF OUTPUT

A listing of sample output is shown in figure 3. The resulting plots are found in figures 4 through 7. Figures 4 and 5 are the output from IFLAG = 2. Figures 6 and 7 are the output from IFLAG = 1. The first section of output is an echoing of the namelist input variables. This is followed by a schematic drawing of the disturbed region showing grid numbers and the coordinates of the center of the corner meshes. The next section shows additional input parameters: the identification label that will be on the plots, the frequency, conductivity, dielectric function, and the complex eigenangle and excitation factor for each region. YMID represents the y-value coordinate of the midpoint of the disturbance.

In the printout, the tables for WI, EZO, and EZS, are the magnitudes of the quantities as given by equations 9, 10, and 13. These quantities are computed at the midpoints of each grid square.

The last table in the printout lists the following quantities at the given distance from the transmitter along the x-axis at y=0:

EZREL, EZANG magnitude(dB) and phase angle (radians) of equation 8

WMAG, WANG magnitude(dB) and phase angle (radians) of equation 9

EZUMAG, EZUANG magnitude(dB) and phase angle (radians) of equation 10

EZPMAG, EZPANG magnitude(dB) and phase angle (radians) of equation 13

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SENTER	CENTER	SENTER.	CENTER
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ATES	ATES	ATES	ATES
COORDIN	COORDINATES AT CENTER OF MESH NUMBER 4 ARE: X= 2187.50 Y= 437.50	COORDIN	COORDIN

Figure 3. Sample printed output generated by the first case called out in the sample data.

Figure 3. Continued

Figure 3. Continued.

6,00698+00	5.72824+00	3.44950+00	5.17075+00	1 Re199+00	4.61323+00	4.33447+00	4.05570+00	3.77693+00	1.42816+00	3.21939+00	1.94063+00	2.66186+00	38310+00	2.10434+00	1.82558+00	1.54683+00	1.26809+00	9.89353-00	7.10626-00	4.31909-00	1.53204-00	6.15770+00	5.87902+00	5.60036+00
1.11831+001	1,10719+001	1.09632+001	1.09572+001	1.07538+001	1.06531+001	1.05551+001	1.04599+001	1,03676+001	1.02781+001	1.01917+001	_	1.00280+001	9.95089+000		9.80671+000	9.73982+000	9.67655+000	_		9.50976+000			9.38074+000	9.34699+000
2.99327+000	2.71397+000	2.43465+050	2.15535+000	1.87533+000	1.59670+000	1.31737+000	1.03804+000	7.58698-001	4.79354-001	2.00006-001	6.20384+000	5.92448+000	5.64512+000	5.36576+000	5.00639+000	4.80702+000	4.52765+000	4.24827+000	3.96889+000	3.68951+000	3.41012+000	3.13073+000	2.85134+000	2.57194+000
1,23423+001	1,22768+001	1,21639+001	1,20536+001	1,19459+001	1,18408+001	1,17385+001	1,16389+001	1,15422+001	1,14482+001	1.13572+001	1,12692+001	1.11843+001	1,11025+001	1,10239+061	1.09486+001	1.05767+001	1.08083+001	1.07436+001	1.06826+001	1,06255+001	1.05725+001	1,05237+001	1.04792+001	1.04394+001
3.01371+000	3.0142/+000	3.01484+000	3.01540+000	3.01595+000	3.01653+039	3.01709+000	3.01766+000	3.01323+000	3.01881+000	3.019394000	3.01997+000	3.02056+000	3.02116+000	3.02176+000	3.02237+000	3.02300+000	3.02363+000	3.52427+000	3.02492+000	3.02559+000	3.02627+000	3.02697+000	3.02768+000	3.02842+000
-1.20918+003	-1.20494+000	-1.2006#+000	-1.19641+000	-1.19211+000	-1.18778+000	-1.18342+060	-1.17903+000	-1,17459+000	-1.17011+000	-1,16557+000	-1.16097+000	-1,15630+030	-1,15157+000	-1.14675+000	-1,14185+000	-1,13685+090	-1.13176+000	-1.12655+000	-1.12122+000	-1.11576+000	-1.11016+000	-1.10441+000	-1.09850+000	-1.09240+000
6,15530+000	۳,	6.15643+000	6.15699~000	6,15756+000	6, 15812+000	6.15869+000	6.15926+000	5	5.16040+000	6.16098+000	6.16157+000	6.16216+000	6.16275+000	=	6.16397+000	6.16459+000	6.16322+000	6.16586+000	6.16651+000	=	6.16786+000	6.16856+000	6.16928+000	6.17001+000
-1.20 +1 u+000	-1.20494+000	-1,20069+300	-1.19641+000	-1.192111+000	-1.18778+000	-1.183.12+000	-1.17403+000	-1,17459+000	-1.17011+000	-1.16557+000	-1.16047+000	-1.15630+000	-1.15157+000	-1.14675+000	-1.14185+000	-1.13585+000	-1.13175+000	-1.12655+000	-1.12122+000	-1.11576+000	-1.11016+000	-1.10441+000	-1.09850+000	-1.09240+000
11400.0	11550.0	11700.0	11850.0	12000.0	12150.0	12300.0	12450.0	12600.0	12750.0	12900.0	13050.0	13200.0	13350.0	13500.0	13650.0	13800.0	13950.0	14100.0	14250.0	14400.0	14550.0	14700.0	14850.0	15000.0
0	٥.	0	0	0	0.	0.	0.	0	0.	0.	0.	0.	٥.	٥.	٥.	٥.	0.	٥.	•	0.	٥.	•	•	٥.

PLOTTING COMMENCING

.... DISSPLA VERSION 9.0 ....

NO. OF FIRST PLOT 1

PLOT NO. 1 WITH THE TITLE

HAS BEEN COMPLETED.

PLOT 10. READS

PLOT 1 11.03.23 THUR 23 SEP, 1982

JOB\*SPORAD , DISSPLA 9.0

DATA FOR PLOT

HORIZ. AXIS LENGTH 8.0 INS.

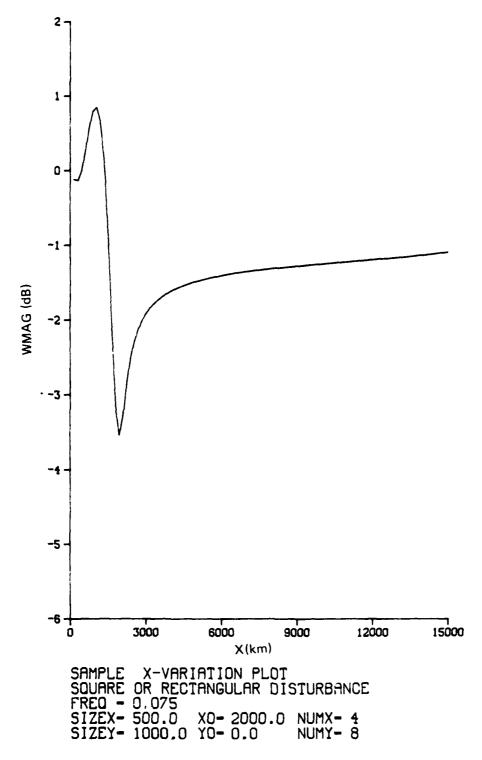


Figure 4. Sample x-variation plot for WMAG assuming a rectangular disturbance.

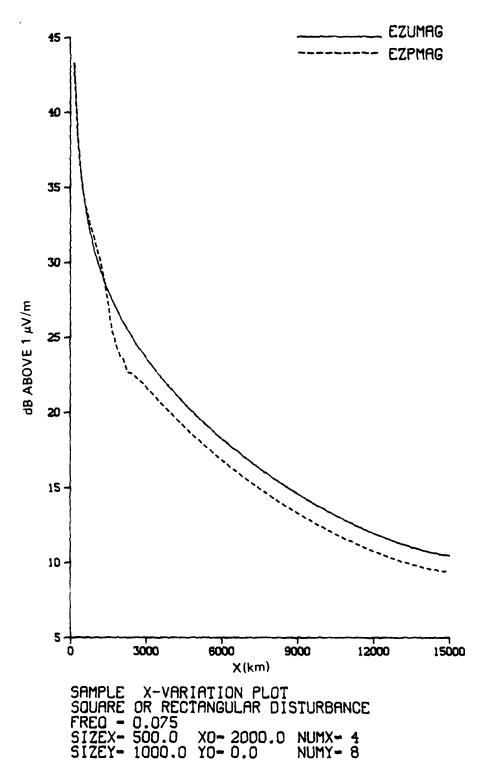


Figure 5. Sample x-variation plot for EZUMAG and EZPMAG assuming a rectangular disturbance.

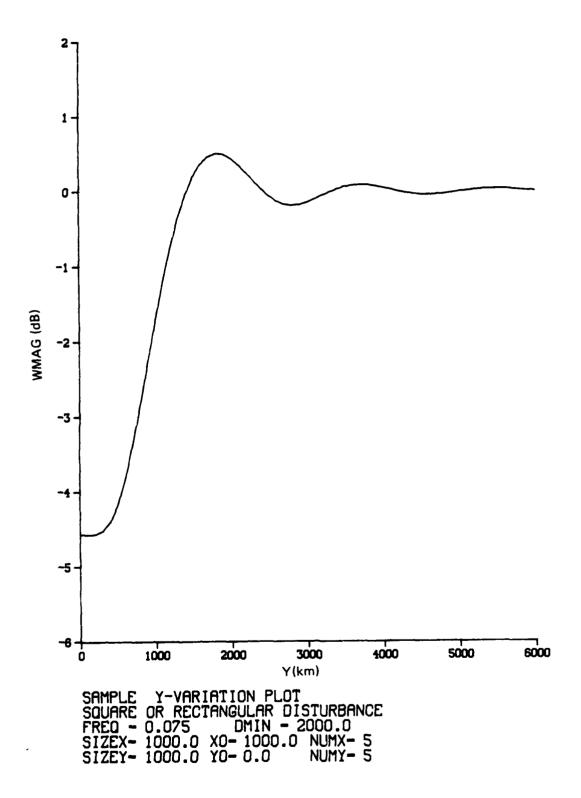


Figure 6. Sample y-variation plot for WMAG assuming a rectangular disturbance.

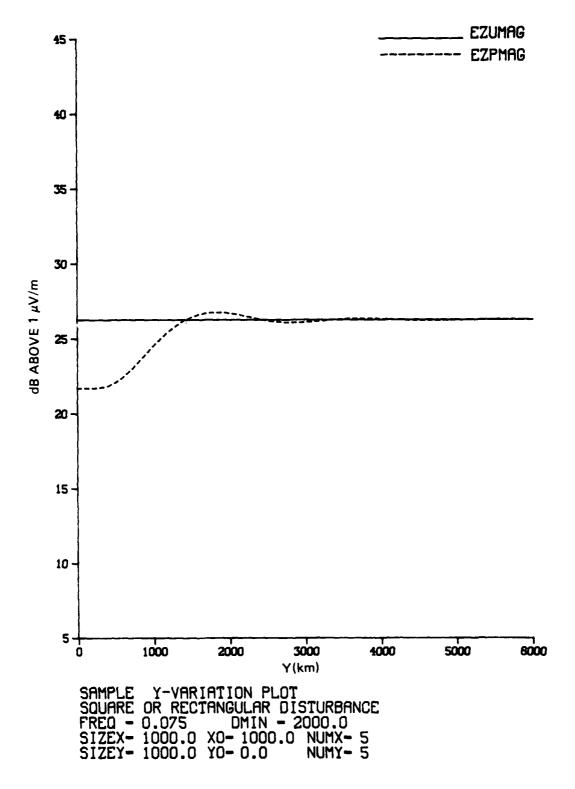


Figure 7. Sample y-variation plot for EZUMAG and EZPMAG assuming a rectangular disturbance.

## VI. PROGRAM CHECKS

Several program checks have been made of flat earth geometry cases which can be solved in terms of well known functions. In each case the disturbance is azimuthally symmetric with the transmitter located at the origin.

The first case considered is that of a uniform circular disturbance for which

$$s^{2} = s_{0}^{2} \quad \text{for } r \leq r_{0}$$

$$s^{2} = s_{0}^{2} \quad \text{for } r > r_{0}$$
(18)

For this case the solution for the ratio of the disturbed lateral function,  $\Psi$  , to the undisturbed,  $\Psi^{1}$  is for  $r < r_0$ 

$$\frac{\Psi}{\Psi^{i}} = \frac{s_{p}}{s_{0}H_{1}^{(2)}(ks_{0}r)} \left\{ H_{1}^{(2)}(ks_{p}r) - \frac{\left(H_{1}^{(2)}(ks_{p}r_{0}) + h(ks_{0}r_{0}) - h(ks_{p}r_{0}) + H_{1}^{(2)}(ks_{0}r_{0})\right)}{\left(J_{1}(ks_{p}r_{0}) + h(ks_{0}r_{0}) - j(ks_{p}r_{0}) + H_{1}^{(2)}(ks_{0}r_{0})\right)} J_{1}^{(ksr)} \right\}$$

and for r>r<sub>0</sub>

$$\frac{\Psi}{\Psi^{i}} = \frac{s_{p}}{s_{0}} \left\{ \frac{H_{1}^{(2)}(ks_{p}r_{0}) \ j(ks_{p}r_{0}) - h(ks_{p}r_{0}) \ J_{1}(ks_{p}r_{0})}{H_{1}^{(2)}(ks_{0}r_{0}) \ j(ks_{p}r_{0}) - h(ks_{0}r_{0}) \ J_{1}(ks_{p}r_{0})} \right\}$$
(20)

In these equations

$$h(x) = \frac{x}{2} \left[ H_0^{(2)}(x) - H_2^{(2)}(x) \right]$$
 (21)

$$j(x) = \frac{x}{2} [J_0(x) - J_2(x)]$$
 (22)

It is clear from equation (20) that  $\psi/\psi^{i}$  is constant for  $r > r_0$  as expected. Figure 8 shows the results calculated by using equation (19) along with the moment method results. The radius  $r_0$  is 500 km. The unperturbed eigenangle is  $(83.985^{\circ}, -34.909^{\circ})$  or equivalently  $S_0 = (1.185, -0.0681i)$  and the perturbed eigenangle is (59.393°,-65.552°) or equivalently  $S_{D} = (1.488,-0.718i)$ .  $S_{0}$  is appropriate to a nighttime ambient ionosphere at 75 Hz, whereas, Sp is appropriate to a nighttime ionosphere with a sporadic E layer $^9$ . The 13 x 13 mesh results give agreement to within a few hundreths of a dB of the exact results. In the moments method, the lateral function is calculated at the center points of each square mesh and the lateral function is linearly interpolated between those points. Because of approximations made in the slab containing the transmitter, the first meaningful data point obtained from the moment method is the first point to fall in a slab adjacent to that containing This explains the starting ranges for the moment method the transmitter. results.

A second check case considered is that of a circular disturbance which is uniform out to a radius  $r_0$ , then falls off as  $1/r^2$  between  $r_0$ , and  $r_1$ , and is equal to  $S_0$  beyond  $r_1$ . The mathematical description of S is

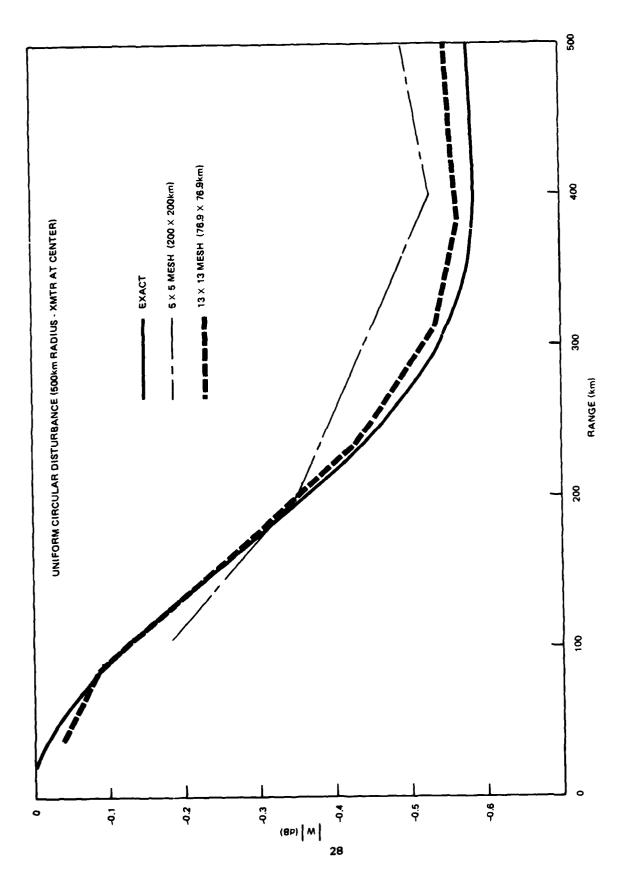


Figure 8. Comparison between analytic solution and the computer program output for problem 1: a uniform circular disturbance.

$$s^{2} = s_{p}^{2} \qquad ; r \leq r_{0}$$

$$s^{2} = s_{0}^{2} + (s_{p}^{2} - s_{0}^{2}) r_{0}^{2} / r^{2} ; r_{0} \leq r \leq r_{1}$$

$$s^{2} = s_{0}^{2} \qquad ; r > r_{1}$$
(23)

When the transmitter is at the center of the disturbance the solution for the ratio of the disturbed lateral function,  $\psi$ , to the undisturbed,  $\psi^i$ , is for  $r < r_0$ 

$$\frac{\psi}{\psi^{i}} = \frac{1}{S_{0}H_{1}^{(2)}(kS_{0}r)} \left[ SH_{1}^{(2)}(kS_{p}r) + aJ_{1}(kS_{p}r) \right] ; r \leq r_{0}$$
 (24)

$$\frac{\psi}{\psi^{i}} = \frac{1}{s_{0}H_{1}^{(2)}(ks_{0}r)} \left[bJ_{v}(ks_{0}r) + dJ_{-v}(ks_{0}r)\right] ; r_{0} < r < r_{1}$$
 (25)

$$\frac{\psi}{\psi^{i}} = \frac{T}{S_0} \qquad ; \quad r < r_1 \tag{26}$$

In these equations

$$v = \left[1 - \left(s_{p}^{2} - s_{0}^{2}\right) \left(kr_{0}\right)^{2}\right]^{1/2}$$
 (27)

$$a = \frac{1}{\Delta} \begin{cases} sH_{1}^{(2)}(ks_{p}r_{0}) & J_{\nu}(ks_{0}r_{0}) & J_{-\nu}(ks_{0}r_{0}) & 0 \\ sh_{1}(ks_{p}r_{0}) & j_{\nu}(ks_{0}r_{0}) & j_{-\nu}(ks_{0}r_{0}) & 0 \\ 0 & J_{\nu}(ks_{0}r_{1}) & J_{-\nu}(ks_{0}r_{1}) & -H_{1}^{(2)}(ks_{0}r_{1}) \\ 0 & j_{\nu}(ks_{0}r_{1}) & j_{-\nu}(ks_{0}r_{1}) & -h_{1}(ks_{0}r_{1}) \end{cases}$$

$$(28)$$

$$b = \frac{1}{\Delta} \begin{pmatrix} -J_{1}(ks_{p}r_{0}) & sH_{1}^{(2)}(ks_{p}r_{0}) & J_{-\nu}(ks_{0}r_{0}) & 0 \\ -j_{1}(ks_{p}r_{0}) & sh_{1}(ks_{p}r_{0}) & j_{-\nu}(ks_{0}r_{0}) & 0 \\ 0 & 0 & J_{-\nu}(ks_{0}r_{1}) & -H_{1}^{(2)}(ks_{0}r_{1}) \\ 0 & 0 & j_{-\nu}(ks_{0}r_{1}) & -h_{1}(ks_{0}r_{1}) \end{pmatrix}$$

$$(29)$$

$$d = \frac{1}{\Delta} \begin{bmatrix} -J_{1}(ks_{p}r_{0}) & J_{v}(ks_{0}r_{0}) & sH_{1}^{(2)}(ks_{p}r_{0}) & 0 \\ -j_{1}(ks_{p}r_{0}) & j_{v}(ks_{0}r_{0}) & sh_{1}(ks_{p}r_{0}) & 0 \\ 0 & J_{v}(ks_{0}r_{1}) & 0 & -H_{1}^{(2)}(ks_{0}r_{1}) \\ 0 & j_{v}(ks_{0}r_{1}) & 0 & -h_{1}(ks_{0}r_{1}) \end{bmatrix}$$
(30)

$$T = \frac{1}{\Delta} \begin{bmatrix} -J_{1}(ks_{p}r_{0}) & J_{\nu}(ks_{0}r_{0}) & J_{-\nu}(ks_{0}r_{0}) & -sH_{1}^{(2)}(ks_{p}r_{0}) \\ -j_{1}(ks_{p}r_{0}) & j_{\nu}(ks_{0}r_{0}) & j_{-\nu}(ks_{0}r_{0}) & sh_{1}(ks_{p}r_{0}) \\ 0 & J_{\nu}(ks_{0}r_{1}) & J_{-\nu}(ks_{0}r_{1}) & 0 \\ 0 & j_{\nu}(ks_{0}r_{1}) & j_{-\nu}(ks_{0}r_{1}) & -h_{1}(ks_{0}r_{1}) \end{bmatrix}$$

$$(31)$$

$$\Delta = \begin{bmatrix} -J_{1}(ks_{p}r_{0}) & J_{\nu}(ks_{0}r_{0}) & J_{\nu}(ks_{0}r_{0}) & 0 \\ -j_{1}(ks_{p}r_{0}) & j_{\nu}(ks_{0}r_{0}) & j_{-\nu}(ks_{0}r_{0}) & 0 \\ 0 & J_{\nu}(ks_{0}r_{1}) & J_{-\nu}(ks_{0}r_{1}) & -H_{1}^{(2)}(ks_{0}r_{1}) \\ 0 & j_{\nu}(ks_{0}r_{1}) & j_{-\nu}(ks_{0}r_{1}) & -h_{1}(ks_{0}r_{1}) \end{bmatrix}$$
(32)

$$j_{q}(x) = \frac{x}{2} \left[ J_{q-1}(x) - J_{q+1}(x) \right]$$
 (33)

$$h_{q}(k) = \frac{x}{2} \left[ H_{q-1}^{(2)}(x) - H_{q+1}^{(2)}(x) \right]$$
 (34)

Again it is clear from equation (26) that  $\psi/\psi^{i}$  is constant for  $r > r_1$ . Figure 9 shows results for  $r_0 = 300$  km,  $r_1 = 1000$  km and the same  $S_0$  and  $S_p$  used for the results of figure 8. The moment method results are for a 10 x 10 mesh and the results beyond 100 km agree with the exact values to better than a tenth of a dB.

A third check based on the model described by equations (23) is shown in figure 10.  $S_0$  and  $S_p$  are assigned the same values as for figure 8; however,  $r_0$  has been taken equal to 588 km and  $r_1 = 2000$  km. The moment method result is for a 17 x 17 mesh which is the largest the program can handle because of storage limitations. The mesh size in this instance is approximately 235 km. In this connection Hagmann et al 13, state that the mesh size must be less than 155  $\lambda_0$  where  $\lambda_0$  is the unperturbed wavelength. In the present case of 75 Hz,  $\lambda_0 \approx 4000/s_{0r} \approx 3375$  km . This would give a maximum cell size of  $\approx 523$  km. It has been our experience that approaching this limit leads to substantial error and it would probably be best at 75 Hz not to exceed mesh sizes of several hundred kilometers. This would limit the linear dimension of the disturbance to something on the order of 5000 km at 75 Hz. Figure 10 shows the agreement between the exact calculation and the moment method to be within a few tenths of a dB. It is also very likely true that the cases checked are some of the most difficult for the moment method to handle because the gradient of the incident field is largest close to the transmitter. Thus, it would be expected that for disturbances remote from the transmitter better accuracy would be obtained for the same mesh size.

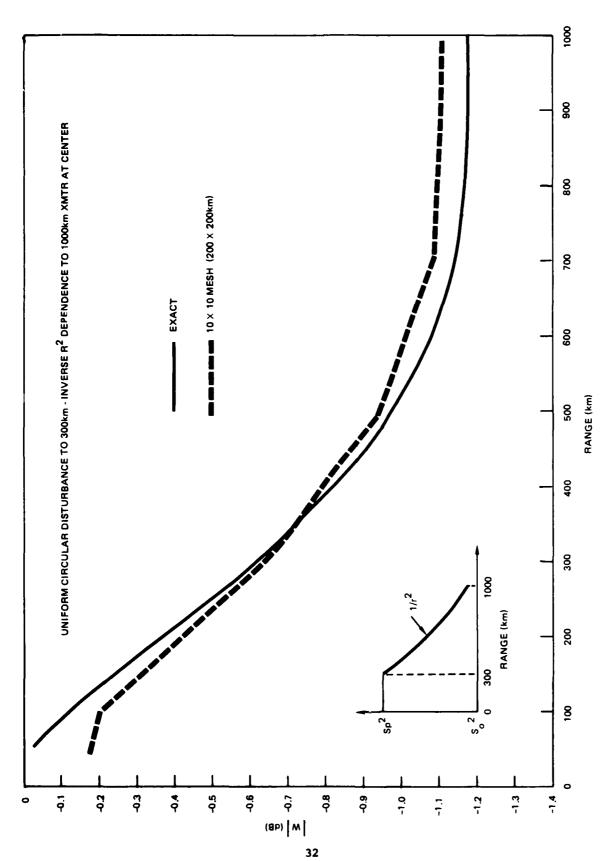


Figure 9. Comparison between analytic solution and the computer program output for problem 2: a uniform circular disturbance to  $r_0$  with an inverse  $r^2$  dependence of  $S_p$  between  $r_0$  and  $r_1$  using a 10  $\times$  10 mesh.

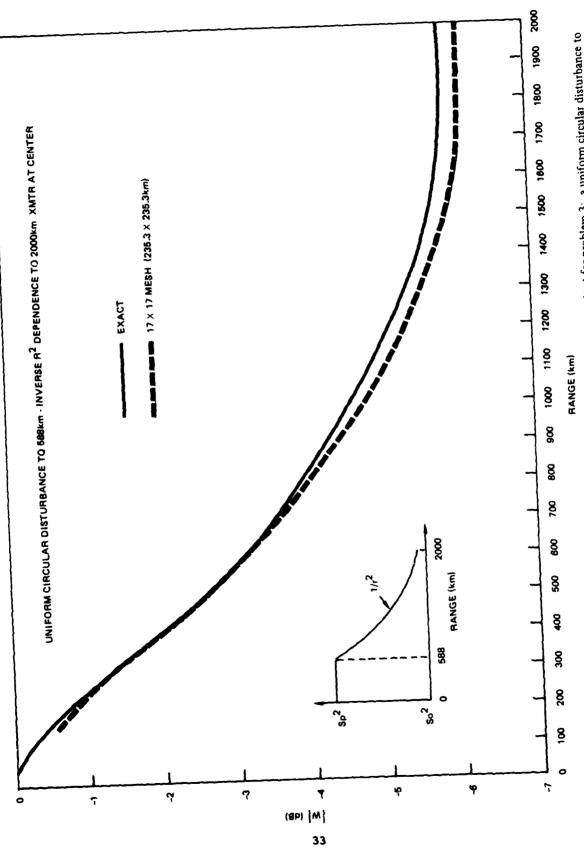


Figure 10. Comparison between analytic solution and the computer program output for problem 3: a uniform circular disturbance to  $_{10}$  with an inverse  $_{10}$  dependence of  $_{10}$  between  $_{10}$  and  $_{11}$  using a  $_{17} \times _{17}$  mesh.

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VIII. APPENDIX: PROGRAM LISTING

```
SPORAD . MAIN
PFTN, USFO
FTN 10R1A
           09/22/82~11:32(9,10)
           1.
                       SPORADIC-E PROGRAM FOR ELF
                 C
           2.
                 С
           з.
           4.
                       IMPLICIT COMPLEX
                                           (A-H, O-Z)
           5.
                 C
           6.
                       PARAMETER MAXNX=12,NDIM=100,NRPTS=500
           7.
                 C
                       MAXNX IS THE MAX NUMBER OF DISTURBED EIGENS WHICH CAN BE INPUT
                 С
           8.
                       NDIM IS THE MAX VALUE OF NUMX+NUMY
                 С
           9.
                       NRPTS IS THE MAX NUMBER OF POINTS TO PLOT
          10.
                 С
          11.
          12.
                       COMPLEX
                                   IM/(0.E0,1.E0)/,J1,J2,NG%FM,K50,NGSQ,
                                   A(NDIM, NDIM).
          13.
          14.
                                   EZO(NDIM), EZS(NDIM), SD(NDIM), XTRD(NDIM), WI(NDIM),
          15.
                      $
                                   SI(MAXNX), XTRI(MAXNX)
                 ¢
          16.
          17.
                       REAL
                                   XM, +M, XGSQ, AI, SIZEX, SIZEY, XDINC, XO, YO, YOVERX, DELTAX,
          18.
                      $
                                   DELTAY.X1, Y1, XINC, YINC, EPSR, RHOMN, EZREL, EZANG, KA, DELY,
          19.
                                   YMAX, F, WMAG, WANG, YMID, OMEGA, RADIUS, WAVENO, FREQ, SIGMA,
          20.
                                   ERP. DIST, DMIN, DM, DELD, DMAX, HXINC, HYINC, RG, AIMAX, DST,
                                   RGMAX.RGMIN.EZUMAG.EZUANG.EZPMAG.EZPANG.PI.DTR.EPSO.
          21.
          22.
                                   X3(4),YG(4),
          23.
                                   X(NDIM), Y(NDIM), CLNQ(NDIM), XX(NDIM), YY(NDIM),
          24.
                                   XI(MAXNX), YI(MAXNX),
          25.
                                   XPLOT(NRPTS), Y1PLOT(NRPTS), Y2PLOT(NRPTS), Y3PLOT(NRPTS),
          26.
                                   EXTIC, EYTIC, WXTIC, WYTIC, XMAX, XLNG, YLNG, WMIN, WMAX, EMIN,
          27.
          28.
                 С
          29.
                       INTEGER
                                   TROW(NDIM)
          30.
                 С
          31.
                       CHARACTER+1 LABELO/'?'/
          32.
                       CHAPACTER+4 ID(20)
                        CHAP CTER+5 LABEL1/
                                                 ?'/. LABEL2/'___?'/,LABEL3/'___ '/
          33.
          34.
                       CHARACTER*8 KLABEL
          35.
                       CHARACTER+36 LABEL
                 С
          36.
          37.
                       COMMON/ONE/H12, H22, J1, J2, S0, ARGO, KA, KS0
          38.
                       COMMON/LABELS/ID, LABEL, XLABEL
          39.
                       CONTON/INPUT/FREG.DMIN.DMAX.SIZEX.SIZEY.XO.YO.EXTIC.EYTIC.WXTIC.
          40.
                                     WYTIC, XLNG, YLNG, EMIN, EMAX, WMIN, WMAX, XMAX, NUMX, NUMY,
          41.
                                     IFLAG
          42.
                       COMMON/PLDA (A/XPLOT, Y1PLOT, Y2PLOT, Y3PLOT, NPTS
          43.
          44.
                       DM - DIPOLE MOMENT IN AMPERE-METERS
          45.
                 ¢
                       DMIN - MINIMUM RANGE (KM) FOR DISTANCE VARIATION
          46.
                        DMAX - MAXIMUM RANGE (KM) FOR DISTANCE VARIATION
          47.
                       DELD - INCREMENT (KM) FOR DISTANCE VARIATION
          48.
                 С
                        YMAX - MAXIMUM OFF-AXIS VALUE (KM) FOR Y VARIATION
          49.
                        DELY - INCREMENT (KM) FOR Y VARIATION
          50.
                        IFLAG=1 Y VARIATION
                 C
          51.
                 C
                        IFLAG=2 DIST VARIATION
          52.
                 C
                        IGRID = 0 SQUARE OR RECTANGULAR DISTURBANCE
          53.
                        IGRID = 1 CIRCULAR OR ELLIPTICAL DISTURBANCE
          54.
                 С
                       XO.YO - COORDINATES (KM) AT CENTER OF DISTURBANCE
          55.
                                YO IS ALSO INITIAL VALUE FOR Y VARIATION
```

```
NUMX, NUMY - THE DISTURBANCE IS DIVIDED INTO NUMX GRIDS IN THE X DIRECTION AND NUMY GRIDS IN THE Y DIRECTION SIZEX, SIZEY - DEFINES THE PHYSICAL SIZE OF THE DISTURBANCE - IT IS
 56.
 57.
        C
 58.
 59.
                                  SIZEX KM BY SIZEY KM
                IPLOT=0 DON'T PLOT
 60.
        Ċ
 61.
                IPLOT=1
                          PLOT
                XLNG, YLNG - LENGTH (INCHES) OF X-AXIS AND Y-AXIS RESPECTIVELY
        C
 62.
                WMIN, WMAX - MINIMUM AND MAXIMUM (DB) FOR Y-AXIS OF WMAG PLOT
EMIN, EMAX - MINIMUM AND MAXIMUM (DB) FOR Y-AXIS OF EZ PLOT
 63.
        С
 64.
        С
 65 .
                EXTIC, EYTIC - UNITS PER TIC MARK ALONG X AND Y AXIS RESPECTIVELY
                                  FOR EZ PLOTS
 66.
 67.
                WXTIC.WYTIC - UNITS PER TIC MARK ALONG X AND Y AXIS RESPECTIVELY
 68.
                                  FOR WMAG PLOTS
 69.
                NAMELIST/DATUM/DM, DMIN. DMAX, DELD, YMAX, DELY, IFLAG, IGRID,
 70.
 71.
               $
                                   XO, YO, NUMX, NUMY, SIZEX, SIZEY, IPLOT, XLNG, YLNG,
 72.
               $
                                   WMIN, WMAX, EMIN, EMAX, EXTIC, EYTIC, WXTIC, WYTIC
 73.
        C
 74.
                DATA IPLOT/0/
                DATA PI/3.14159265358979E0/,DTR/.017453292E0/,EPS0/8.85434E-12/
DATA XLNG/5./,YLNG/6./,WMIN/-6./,WMAX/2./,EMIN/-6./,EMAX/2./
 75.
 76.
                DATA EXTIC/200./,EYTIC/5./,SIZEX/1.E3/,SIZEY/1.E3/
DATA WXTIC/200./,WYTIC/1./
 77.
 78.
 79.
                DATA DMIN, 25.E0/, DMAX/1000.E0/, DELD/25.E0/
                DATA YMAX/500.E0/,DELY/25.E0/,X0/0.E0/,Y0/0.E0/
 80.
                DATA DM/6.75E6/
 81.
                DATA IFLAG/2/, IGRID/0/
 82.
                DATA CONST/(-.707106781186548E0,-.707106781186548E0)/
83.
 в4.
        С
 85.
        C
 86.
                DEFINE CAPG2(ARG) = PI/(2.0E0* SIN(ARG/6371.0E0))
 87.
        C
                PRINT 915
 B8 .
                READ(5, DATUM)
 89.
 90.
                WRITE(6, DATUM)
 91.
        C
 92.
                NU = NUMX * NUMY
 93.
                IF(NU .GT. NDIM)
 94.
                 THEN
 95.
                          PRINT 971
 96.
                          STOP
                ENDIF
 97.
 98 .
                NPTS = 0
                DIST = DMIN
 99.
100.
                YMID = YO
101.
                SET UP DISTURBED REGION GRID
102.
                XINC = SIZEX/NUMX
103.
104.
                HXINC = .5+XINC
                YINC = SIZEY/NUMY
HYINC = .5+YINC
105.
106.
107.
108.
                GRID ELEMENTS MUST BE SQUARE
                IF(XINC .NE. YINC)
109.
               $
110.
                    THEN
111.
                          PRINT 976
112.
                          STOP
```

```
1
       113.
                      ENDIF
       114.
                      YOVERX = SIZEY/SIZEX
       115.
                      X1 = X0-0.5E0*(SIZEX-XINC)
       116.
                      Y1 = Y0+0.5E0+(SIZEY-YINC)
       117.
                      RADIUS = SQRI((XINC+YINC)/PI)
       118.
                      XX(1) = X1
       119.
                      DO 12 I=2, NUMX
       120.
                      XX(1) = XX(1-1) + XINC
1
               12
       121.
                      YY(1) = Y1
                      DO 13 J=2. NUMY
       122.
               13
                      YY(J) = YY(J-1)-YINC
       123.
1
       124.
                      00 15 J=1, NUMY
00 15 I=1, NUMX
       123.
       126.
2
       127.
                      M = M+1
                      X(M) = XX(I)

Y(M) = YY(J)
       128.
2 2
        129.
               15
       130 .
                      CONTINUE
2
        131.
               С
                      PRINT SCHEMATIC OF DISTURBED REGION GRID
2
        132.
               С
                      IF(NUMY .GT. 10) PRINT 915
        133.
        134.
                      PRINT 920
        135.
                      PRINT 930, (LABEL3, J=1, NUMX)
        136.
                      00 18 K=1, NUMY
        137.
                      PRINT 910, LABELO, (LABEL1, J=1, NUMX)
        138.
                      PRINT 940, LABELO, ((K-1)+NUMX+J, LABELO, J=1, NUMX)
                      PRINT 910, LABELO, (LABEL1, J=1, NUMX)
        139.
        140.
                      PRINT 910, LABELO, (LABEL2, J=1, NUMX)
        141.
               18
                      CONTINUE
        142.
        143.
               Ċ
                      PRINT CODRDINATES OF GRID
                      PRINT 920
        144.
        145.
                      N = 1
        146.
                      WRITE(6,100) N.X(N),Y(N)
        147.
                      WRITE(6,100) NUMX,X(NUMX),Y(NUMX)
        148.
                      N = NU-NUMX+1
                      WRITE(6,100) N,X(N),Y(N)
        149.
        150.
                      WRITE(6,100) NU,X(NU),Y(NU)
        151.
        152.
                      READ GRID DATA
        153.
               C
        154.
                      MODE PARAMETERS ARE FROM USING NPUNCH=1 IN
        155.
               C
                      THE WAVEGUID OR MODESRCH COMPUTER PROGRAMS
        156.
                      READ 1000.10
        157.
                      PRINT 1001, ID
        158.
               Ç
        159.
                      AMBIENT
        160.
                      READ 1010, FREQ, SIGMA, EPSR
                      PRINT 1011. FREQ. SIGMA, EPSR
        161.
                      OMEGA=6.28318530717959E3*FREQ
        162.
                      WAVENO = .020958445E0 + FREQ
        163.
                      NGSQ = SIGMA/(IM+OMEGA+EPSO)+EPSR
        164.
                      NGXTM = C SQRT(NGSQ)
        165.
        166.
                      IF(DREAL(NGXTM) .LT. 0.0E0) NGXTM=-NGXTM
        167.
                      EXO = 1.0EO/NGXTM
                      ECGNST= .03248E6+DM+EX0+WAVEND++2/(5.0E3+ SQRT(FREQ))
        168.
        169.
                      N = 0
```

```
170.
                       PRINT 1009
                       READ 1020, THETAO, TMP1
        171.
                       THTAO = THETAO+DTR
SO = C SIN(THTAO)
        172.
        173.
                       CSQ = (1.E0,0.E0)-S0**2
C = C SQRT(CSQ)
        174.
        175.
        176.
                       SQROOT = C SQRT(NGSQ-CSQ)
                       XTRAO = -4.0*IMP1*SO
PRINT 1021,N.THETAO,XTRAO
        177.
        178.
                       KA = WAVENOTRADIUS
        179.
        180.
                       KS0 = WAVENO+SO
        181.
                       ARGO = KSO+RADIUS
        182.
                       CALL CBESJY(ARGO, 1, BJ, BY, 0, 0)
                       H12 = BJ- IM+BY
        183.
        184.
                       J1 = BJ
        185.
                       CALL CBESJY(ARGO, 2, BJ, BY, 0, 0)
        186.
                       H22 = BJ-IM+BY
        187.
                       J2 = BJ
        188.
        189.
                       DISTURBED
                       READ 1010, F
IF(F .NE. 0.)
        190.
        191.
        192.
                          THEN
                                N = N+1
        193.
1
        194.
                                IF(N .EQ. MAXNX)
        195.
                                    THEN
2
        196.
                                          PRINT 974
        197.
                                          STOP
2
                                ENDIF
        198.
        199.
                                READ 1020, THETAP, TMP1
                                THTAP = THETAP*DTR
SP = C SIN(THTAP)
        200.
        201.
        202.*
                                XTRAP=-4.0+TMP1+SP
        203.
                                PRINT 1021, N. THETAP, XTRAP
        204.
                                SI(N) = SP
        205.
                                XTRI(N) = XTRAP
                                GO TO 25
        206.
        207.
                          ELSE
        208.
                                NMAX = N
        209.
                       END IF
                C
        210.
        211.
                       IF(NMAX .EQ. 1)
                          THEN
        212.
                C
                                UNIFORM DISTURBANCE
        213.
1
        214.
                                NMAX = 2
        215.
                                SI(2) = SP
        216.
                                XTRI(2) = XTRAP
                       END1F
        217.
        218.
                       SET UP INTERPOLATION ARRAYS
        219.
                С
                       XDINC = 0.5E0*SIZEX/(NMAX-1)
        220.
        221.
                       DO 33 N=1,NMAX
        222.
                       XI(N) = XDINC*(N-1)
        223.
                33
                       YI(N) = YOVERX+XI(N)
        224.
                C
        225.
                C
                       FILL GRID OF SD AND XTRD
        226.
                       IF(IGRID .EQ. 0)
```

1

```
227.
                          THEN
        228.
                                SQUAPE OR RECTANGLE
        229.
               C
                                A RECTANGLE CAN ONLY BE UNIFORMLY DISTURBED
        230.
                                A SQUARE CAN HAVE A NON-UNIFORM DISTURBANCE LABEL = 'SQUARE OR RECTANGULAR DISTURBANCE
        231.
        232.
        233.
                                DO 39 M=1,NU
                                XM = ABS(X(iA)-XO)

YM = ABS(Y(M)-YO)
2
        234.
2
        235.
                                IF(XM .GT. .5E0+SIZEX .OR. YM .GT. .SE0+SIZEY)
        236.
2
        237.
                                   THEN
3
                                        SD(M) = SO
        238.
3
        239.
                                        XTRD(M) = XTRAO
3
        240.
                                   ELSE
3
        241.
3
        242.
                                        K = 1
        243.
3
        244.
                35
                                        IF(XM .LE. XI(I+1)) GO TO 37
        245.
3
                                        I = I+1
                                        GO TO 35
3
        246.
3
        247.
                37
                                        IF(YM .LE. YI(K+1)) GO TO 38
        248.
        249.
                                        GO TO 37
                                        IF(I .GT. K)
        250.
                38
3
                                           THEN
        251.
4
                                                SLOPE = (XM-XI(I))/(XI(I+1)-XI(I))
        252.
        253.
                                                SD(M) = SI(I)+(SI(I+1)-SI(I))*SLOPE
4
        254.
                                                XTRD(M) = XTRI(I) + (XTRI(I+1) - XTRI(I)) + SLOPE
        255.
                                           ELSE
                                                SLOPE = (YM-YI(K))/(YI(K+1)-YI(K))
        256.
                                                SD(M) = SI(K)+(SI(K+1)-SI(K))+SLOPE
        257.
4
                                                XTRD(M) = XTRI(K) + (XTRI(K+1) - XTRI(K)) + SLOPE
        258.
4
        259.
                                        ENDIF
3
        260.
                                ENDIF
3
        261.
                                CONTINUE
        262.
                39
        263.
                С
        264.
                          ELSE
        265.
                C
                                ELLIPSE OR CIRCLE
        266.
                                LABEL = 'CIRCULAR OR ELLIPTICAL DISTURBANCE '
        267.
                                AIMAX = XI(NMAX)
                                DO 59 M=1,NU
        268.
                                CUGRES OF CENTER OF GRID RELATIVE TO CENTER OF DISTURBANCE
        269.
                C
2
        270.
                                OX-(M)X = MX
        271.
                                CY-(M)Y = MY
2
        272.
                С
                                COORDS OF CORNERS OF GRID
2
        273.
                                XG(1) = XM-HXINC
        274.
                                XG(2) = XM + HXINC
        275.
                                XG(3) = XG(1)
                                XG(4) = XG(2)
        276.
2
        277.
                                YG(1) = YM+HYINC
2
        278.
                                YG(2) = YG(1)
2
        279.
                                YG(3) = YM-HYINC
        280.
                                YG(4) = YC(3)
                                RGMAX = -1.0E6
RGMIN = 1.0E6
        281.
        282.
        283.
                                DU 45 I=1,4
```

```
RANGE OF EACH CORNER FROM CENTER OF DISTURBANCE
       284.
       285.
                               RG
                                        SQRT(XG(1)**2+(YG(1)/YOVERX)**2)
                               RGMAX = AMAX1(RGMAX,RG)
       286.
               45
                               RGMIN = AMIN1 (RGMIN, RG)
       287.
                               IF(RGMIN .GE. AIMAX)
       288.
                                  THEN
       289.
2
               C
                                        GRID IS COMPLETELY OUTSIDE OF DISTURBANCE
       290.
       291.
                                        SD(M) = SO
                                        XTRD(M) = XTRAO
       292.
       293.
3
                                        IF(RGMAX .LE. AIMAX)
       294.
       295.
                                           THEN
                                               GRID IS COMPLETELY INSIDE OF DISTURBANCE
               C
3
       296.
       297.
       298.
                                                AI = SQRT(XM**2+(YM/YOVERX)**2)
       299.
               50
                                                IF(AI .LE. XI(I+1)) GO TO 51
                                                I = I+1
       300.
                                               GO TO 50
       301.
                                               SLOPE = (AI-XI(I))/(XI(I+1)-XI(I))
SD(M) = SI(I)+(SI(I+1)-SI('))*SLOPE
       302.
               51
       303.
       304.
                                                XTRD(M) = XTRI(I)+(XTRI(I+1)-XTRI(I))*SLOPE
       305.
                                                GRID IS ON BORDER OF THE DISTURBANCE
       306.
                                                DIVIDE GRID INTO 16 SUBSQUARES
       307.
                                                DELTAX = XINC/B.
       308.
                                               DELTAY = YINC/8.
       309.
       310.
                                                XG(1) = (XM-DELTAX+3.)++2
       311.
                                                XG(2) = (XM-DELTAX
                                                                       ) * * 2
                                                XG(3) = (XM+DELTAX)
       312.
                                                XG(4) = (XM+DELTAX+3.)++2
       313.
                                                YG(1) = ((YM+DELTAY+3.)/YOVERX)++2
       314.
                                                                       )/YOVERX)**2
                                                YG(2) = ((YM+DELTAY
       315.
       316.
                                                YG(3) = ((YM-DELTAY
                                                                        )/YOVERX)*+2
       317.
                                                YG(4) = ((YM-DELTAY+3.)/YOVERX)++2
                                                COUNT NUMBER OF SUBSQUS WITHIN DISTURBANCE
       318.
               ¢
       319.
                                                N = 0
                                                DO 55 I=1,4
       320.
                                                XGSQ = XG(I)
       321.
                                               DO 55 J=1.4
RG = SQRT(XGSQ+YG(J))
       322.
       323.
       324.
                                                IF(RG .LE. AIMAX) N=N+1
                                               SLOPE = N/16.
SD(M) = S0+(SI(NMAX)-S0)*SLOPE
       325.
       326.
                                                XTRD(M) = XTRAO+(XTRI(NMAX)-XTRAO)+SLOPE
       327.
                                        ENDIF
       328.
                               ENDIF
       329.
       330.
                               CONTINUE
                      ENDIF
       331.
               C
       332.
                      SET UP A
       333.
               C
                      DO 55 M±1,NU
DO 65 N±1,NU
       334.
       335.
       336.
                      A(M,N) = CAPA(SD(N),SQRT((X(M)-X(N))**2+(Y(M)-Y(N))**2))
               65
2
       337.
               70
                      MGRID = 0
       338.
                      DO 79 M= 1,NU
NGRID = 0
       339.
1
       340.
```

```
341.
              XM = X(M)
342.
              YM = Y(M)
              IF (XM+ HXING .LT. 0.0EO .DR. XM- HXING .GE. 0.0EO .OR.
343.
                 YM+ HYINC .LT. Q.CEO .OR. YM- HYINC .GE. Q.OEO) GO TO 75
344.
              XMIR IS INSIDE GRID
345.
              GRID POINT IS DISTURBED
346.
              XG(1) = XM-.25*XINC
347.
348.
              XG(3) = XG(1)
              XG(2) = XM+.25*XINC
349.
350.
              XG(4) = XG(2)
              YG(1) = YM + .25 * YINC
351.
352.
              YG(2) = YG(1)
              YG(3) = YM-.25*YINC
353.
              YG(4) = YG(3)
354.
              MGRID = M
355.
              PRINT 955,M
356.
357.
              NQUAD = 0
              SUM = 0.000
358.
359.
              NQUAD = NQUAD+1
              IF(XG(NQUAD)+,125*XINC .GE. 0.0E0 .AND.
360.
                 XG(NQUAD)-.125+XINC .LT. 0.0E0 .AND.
361.
                 YG(NQUAD)+.125+YINC .GE. 0.0E0 .AND.
362.
                 YG(NQUAD)-, 125*YINC .LT. 0.0E0) GO TO 71
363.
              NGRID = NGRID+1
364.
              XM = XG(NQUAD)
365.
              YM = YG(NQUAD)
366.
367.
       75
              RHOMN = SQRT(XM**2+YM**2)
              ARGU = KSO+RHOMN
368.
              CALL CBESUY(ARGU, 1, BJ, BY, 0, 0)
369.
              H12 = BJ-IM+BY
370.
              IF(XM .EQ. 0.0E0) XM-1.0E-6
371.
              EZO(M) = C SQRT(ARGU*CAPG2(RHOMN))*CONST*H12*XM/RHOMN
372.
373.
              IF(NGRID .EQ. 0) GD TD 78
              SUN = SUM+E20(M)
374.
              IF(NQUAD .LT. 4) GO TO 71
375.
              EZO(M) = SUM/NGRID
376.
              IF(C ABS(EZG(M)) .LE. 1.0E-6) EZO(M)=1.0E-21
       78
377.
378.
       79
              CONTINUE
379.
380.
              PRINT TABLE OF EZO
              WRITE (6,110) YMID
381.
              WRITE (6,113)
382.
              DD 81 I=1, NUMY
383.
              WRITE(6,112) (C ABS(EZO(NUMX*(I-1)+J)),J=1,NUMX)
384.
385.
       81
              CONTINUE
386.
387.
        C
              SOLVE FOR SCATTERED FIELDS
388.
              CALL CLINEG(A, EZO, EZS, IROW, CLNQ, NU, NDIM, NPTS, ERR)
       С
389.
              PRINT TABLE OF EZS
390.
              WRITE (6,111)
DO 83 I=1, NUMY
391.
392.
              WRITE(6,112) (C ABS(EZS(NUMX*(I-1)+J)),J=1,NUMX)
393.
394.
        83
              CONTINUE
395.
              DO 85 M=1,NU
396.
397.
              RATIO = EZS(M)/EZO(M)
```

```
IF(MGRID .EQ. M) RATID=1.0
      398.
                     WI(M) = C LOG(RATIO)
       399.
                     CONTINUE
       400.
              85
       401.
                     PRINT TABLE OF WI
       402.
                      WR1TE(6, 102)
       403.
                      DO 87 I=1, NUMY
       404.
                      WRITE(6,103) (REAL(WI(NUMX*(I-1)+J))*8.686,J=1,NUMX)
       405.
               87
                      CONTINUE
       406.
       407.
               С
                      WRITE (6,950)
       408.
                     DIST = DMIN
NPTS = NPTS+1
       409.
       410.
               90
                      IF(NPTS .GT. NRPTS)
       411.
       412.
                         THEN
                               PRINT 973
       413.
                               STOP
       414.
                      ENDIF
       415.
               C
       416.
                      ARGU = KSO+DIST
       417.
                      CALL CBESUY(ARGU, 1.BJ, BY, 0,0)
       418.
                      H12 = BJ-IM+BY
       419.
                      EZU = C SQRT(ARGU*CAPG2(DIST))*CONST*H12
       420.
                      IF(XX(1)-HXINC .GE. DIST .OR. XX(NUMX)+HXINC .LE. DIST .OR. YY(1)+HYINC .LE. 0.E0 .OR. YY(NUMY)-HYINC .GE. 0.E0)
       421.
       422.
                         THEN
       423.
                               RCVR IS OUTSIDE OF DISTURBED AREA
               C
       424.
                               XTRA2 = XTRAO
       425.
                               SUM = (0.0E0,0.0E0)
       426.
                               DO 95 N=1.NU
       427.
                               RHOMN = SQRT((DIST-X(N))**2+Y(N)**2)
       428.
                               SUM = SUM+CAPA(SD(N), RHOMN) *EZS(N)
       429.
                               CONTINUE
       430.
               95
2
                                EZ = EZU~SUM
       431 .
                                RATIO = EZ/EZU
       432.
                                WMAG = 20.0E0+ALOG10(C ABS(RATIO))
       433.
                               WANG = C ANG(RATIO)
       434.
                          ELSE
        435.
                                RCVR IS IN DISTURBED AREA
        436.
               С
        437.
                                DO 96 J=1.NUMX
        438.
                                IF(XX(J)-HXINC .LT. DIST .AND. DIST .LE. XX(J)+HXINC)
        439.
2
                     $
                                GO 10 97
        440.
2
                                I = I+1
        441.
                                CONTINUE
                96
2
        442.
                97
        443.
                                DO 98 J=1, NUMY
        444.
                                IF(YY(J)-HYINC .LT. 0.EO .AND. 0.EO .LE. YY(J)+HYINC)
GO TO 99
        445.
        446.
                                K = K+1
        447.
                                CONTINUE
2
        448.
                                M = (K-1)+NUMX+I
XTRA2 = XTRD(M)
        449.
                99
        450.
                                EZ = EZU
        451.
                                IF(M .EQ. MGRID) GO TO 130
        452.
                                IF(I .GT. 1) GO TO 120
        453.
        454.
```

```
455.
                               N2 = M+1
                               IF(K .GT. 1) GO TO 106
       456.
       457.
               105
                               N3 = N1+NUMX
       458.
                               N4 = N3+1
        459.
                               GO TO 125
                               IF(K .EQ. NUMY) GO TO 108
       460.
               106
                               IF(YY(K) .GE. 0.) GO TO 109
       461.
               107
                               N3 = N1-NUMX
       462.
               108
       463.
                               N4 * N3+1
       464.
                               GO TO 125
       465.
               109
                               N3 = N1+NUMX
                               N4 = N3+1
        466.
        467.
                               GO TO 125
       468.
               120
                               IF(I .LT. NUMX) GO TO 122
        469.
                               N1 = M-1
       470.
                               N2 = M
       471.
               121
                               IF(K .EQ. 1) GO TO 105
       472.
                                IF(K .EQ. NUMY) GO TO 108
        473.
                               GO TO 107
                               IF(XX(I) .LE. DIST) GO TO 123
        474.
               122
       475.
                               N1 = M-1
       476.
                               N2 = M
                               GO FO 121
        477.
       478.
               123
                               N1 = M
        479.
                               N2 = M+1
                               GO TO 121
        480.
                               SLOPE = -Y(N1)/(Y(N3)-Y(N1))
        481.
               125
                               W1 = WI(N1)+(WI(N3)-WI(N1))+SLOPE
       482.
                               W2 = WI(N2)+(WI(N4)-WI(N2))*SLOPE
        483.
                               IF(1 .EQ. NUMX .AND. DIST .GT. x(N2) .OR.
I .EQ. 1 .AND. DIST .LT. x(N1))
       484.
       485.
       486.
                                   THEN
                                        IF(I .EQ. 1)
       487.
                                            THEN
       488.
3
       489.
                                                 DST = XO-.5*SIZEX
       490.
                                                 DELTAX = HXINC
3
       491.
                                                  W2 = W1
       492.
3
                                                 N2 = N1
       493.
3
       494.
                                                  DST = X0+.5*SIZEX
3322222
       495.
                                                  DELTAX = -HXINC
                                         ENDIF
       496.
                                         ARGU = KSO+DST
       497.
       498.
                                         CALL CBESUY(ARGU, 1, BJ, BY, 0, 0)
       499.
                                         H12 = BJ-IM+BY
       500.
                                         EZ1 = C SQRT(ARGU+CAPG2(DST))+CONST+H12
       501.
                                         SUM = (0.0E0, 0.0E0)
                                         DO 126 N=1,NU
2
3
3
       502.
       503.
                                         RHOMN = SQRT((DST - X(N))**2+Y(N)**2)
                                         SUM = SUM+CAPA(SD(N), RHOMN) *EZS(N)
       504.
3
       505.
               126
                                         CONTINUE
2
2
                                        W1 = CLOG((1.0,0.0)-SUM/EZ1)
RATIO = W1+(W2-W1)*(DIST-DST)/DELTAX
       506.
       507.
       508.
       509.
                                         RATIO = W1+(W2-W1)*((DIST-X(N1))/XINC)
2
       510.
                               ENDIF
                               WMAG = REAL(RATIO) +8.686
       511.
```

```
WANG - AIMAG(RATIO)
512.
                        EZ = C EXP(RATIO) +EZU
513.
               ENDIF
514.
515.
        C
516.
        C
        130
              IF(MGRID .EQ. 0)
517.
              $ THEN
518.
        C
                        XMTR IS OUTSIDE OF DISTURBED AREA
519.
                        XTRA1 = XTRAO
520.
521.
                  ELSE
                        XMTR IS IN DISTURBED AREA
        C
522.
                        XTRA1 = XTRD(MGRID)
523.
               ENDIF
524.
        C
525.
               EZUABS = ECONST * EZU*XTRAO
526.
               EZPABS =ECONST +EZ+C SQRT(XTRA1+XTRA2)
527.
               RATIO = EZPABS/EZUABS
528.
               EZREL = 20.0E0 + ALOG10(C ABS(RATIO))
EZANG = C ANG(RATIO)
529.
530.
               EZUMAG = 20.0E0+ALOG10(C ABS(EZUABS))
531 .
               EZUANG = C ANG(EZUABS)
532.
               EZPMAG = 20.0E0+ALOG10(C ABS(EZPABS))
533.
               EZPANG = C ANG(EZPASS)
534.
               WRITE (6,960) YMID, DIST, WMAG, WANG, EZREL, EZANG,
535.
536.
                              EZUMAG, EZUANG, EZPMAG, EZPANG
               YIPLOT(NPTS) = WMAG
537.
               Y2PLOT(NPTS) = EZUMAG
53B.
               Y3PLOT(NPTS) . EZPMAG
539.
540.
               IF(IFLAG .EQ. 2) GO TO 140
541.
542.
        C
               Y VARIATION
               DO 131 N = 1.NU
Y(N) = Y(N)+DELY
543.
544.
        131
545.
               DO 132 J=1, NUMY
               YY(J) = YY(J)+DELY
XPLOT(NPTS) = YMID
XLABEL = 'Y(KM)
546.
        132
547 .
548.
549.
               YMID = YMID+DELY
550.
               IF(YMID .LE. YMAX) GO TO 70
               XMAX = YMAX
551.
               IF(IPLOT .EQ. 1) GO TO 800
552.
553.
               STOP
554.
        Ç
555.
               DISTANCE VARIATION
               XPLOT(NPTS) = DIST
XLABEL = ' X(KM)
        140
556.
557.
               DIST = DIST + DELD
558.
               IF(DIST .LE. DMAX) GO TO 90
559.
               XMAX = DMAX
560.
               IF(IPLOT .EQ. 1) GO TO BOD
561.
562.
563.
        C
               PLOTTING
564.
        800
               CALL DEPLOT
565.
566.
              FORMAT(' COORDINATES AT CENTER OF MESH NUMBER ',13,' ARE: X=1, $ F8.2,' Y=1, F8.2)
567.
         100
568.
```

```
569.
         102
                  FORMAT(/,10X,'WI')
                  FORMAT(1X, 13F10.4)
570.
         103
                  FORMAT(1H0, 'YMID = ', F12.2)
571.
         110
                  FORMAT(/,10X,'EZS')
572.
         111
                  FORMAT((1X,(1P13E10.2)))
573.
         112
                  FORMAT(/, 10X, 'EZO')
574.
         113
575.
         910
                  FORMAT (20X, A1, 13A5)
576.
         915
                  FORMAT('1')
577.
         920
                  FORMAT('0')
                FORMAT(21X,13A5)

FORMAT(21X,13A5)

FORMAT(20X,A1,13(I3,1X,A1))

FORMAT(/,4X,'YMID',5X,'DIST',6X,' WMAG',8X,' WANG',8X,' EZREL',

$ 8X,' EZANG',8X,'EZUMAG',8X,'EZUANG',8X,'EZPANG')
578.
         930
579.
         940
580.
         950
581.
                  FORMAT( 'OXMIR IS INSIDE GRID ',13)
582.
         955
583.
         960
                  FORMAT(2(2X, F7.1), 8(2X, 1PE12.5))
                  FORMAT( ' NU = NUMX + NUMY IS GREATER THAN PARAMETER VARIABLE NDIM')
         971
584.
                 FORMAT( NMAX DOES NOT EQUAL NU OR 1')
FORMAT( NUMBER OF POINTS PLOTTED IS GREATER THAN PARAMETER VARIAB
585.
         972
586.
         973
                $LE NRPTS')
587.
                 FORMAT(' N IS GREATER THAN PARAMETER VARIABLE MAXNX')
FORMAT(' XINC MUST EQUAL YINC')
583.
         974
589.
         976
590.
         1000
                 FORMAT(20A4)
                 FORMAT('1',20A4)
FORMAT('1',20A4)
FORMAT(2X, 'GRID',6X, 'THETA',25X, 'XTRA')
FORMAT(10X,E8.0,34X,E10.0,2X,E5.0)
FORMAT(',FREQ = ',E10.3, 'SIGMA = ',E10.3, 'EPSR=',F7.2)
591.
         1001
592.
         1009
         1010
593.
594.
         1011
595.
         1020
                  FORMAT(1X,2/9.0,1X,2E15.0//)
596.
         1021
                  FORMAT(1X,13,2F10.5,2X,1P2E18.9)
597.
                  END
```

END FTN 2678 IBANK 22972 DBANK 2068 COMMON

```
SUBROUTINE DEPLOT
                   PARAMETER NRPTS=500
                   CHARACTER+8 XLABEL
                   CHARACTER+36 LABEL
                   CHARACTER+4 ID(20)
                   DIMENSION APLOT (NRPTS), YIPLOT (NRPTS), Y2PLOT (NRPTS), Y3PLOT (NRPTS)
                   COMMON/LABELS/ID, LABEL, XLABEL
                   COMMON/INPUT/FREQ, DMIN, DMAX, SIZEX, SIZEY, XO, YO, EXTIC, EYTIC, WXTIC, WYTIC, XLNG, YLNG, EMIN, EMAX, WMIN, WMAX, XMAX, NUMX, NUMY,
                                     TELAG
10
                   COMMON/PLDATA/XPLOT, Y1PLOT, Y2PLOT, Y3PLOT, NPTS
12
                   CALL BGNPL(1)
                   CALL PHYSOR(2.0,2.0)
                                     ',1,XLABEL,8,'WMAG(DB)',8,XLNG,YLNG)
14
                   CALL TITLE(
                   CALL INTAXS
                   CALL YAXANG(0.0)
                   CALL GRAF(O., WXTIC, XMAX, WMIN, WYTIC, WMAX)
                   CALL CURVE(XPLOT, Y1PLOT, NPTS, 0)
18
                   CALL MESSAG(ID,80,0.0,-0.8)
19
                  CALL MESSAG(ID, 80, 0.0, -0.8)

CALL MESSAG(LABEL, 36, 0.0, -1.0)

CALL MESSAG('FREQ = ',7,0.0, -1.2)

CALL REALNO( FREQ, 3, 0.7, -1.2)

IF(IFLAG .EQ. 1) CALL MESSAG('DMIN = ',6,2.0, -1.2)

IF(IFLAG .EQ. 1) CALL REALNO( DMIN, 1, 2.7, -1.2)

CALL MESSAG('SIZEX = X0 = NUMX = ',32,0.0, -1.4)
20
21
22
23
24
25
                   CALL REALNO( SIZEX, 1, 0.7, -1.4)
56
                   CALL REALNO( X0,1,2.0,-1.4)
27
28
                   CALL INTNO(NUMX, 3.7,-1.4)
                                                                        NUMY= ',32,0.0,-1.6)
59
                   CALL MESSAG('SIZEY=
                   CALL REALNO( SIZEY, 1.0.7, -1.6)
CALL REALNO( Y0,1,2.0,-1.6)
31
                   CALL INTHO(NUMY, 3.7,-1.6)
33
                   CALL ENDPL(1)
                   CALL BGNPL(2)
34
35
                   CALL PHYSOR(2.0,2.0)
                   CALL TITLE(' ',1,XLABEL,8.'DB ABOVE 1 MICROVOLT/METER',26,
36
37
                  $ XLNG, YLNG)
                   CALL INTAXS
38
39
                   CALL YAXANG(0.0)
                   CALL GRAF(O., EXTIC, XMAX, EMIN_EYTIC, EMAX)
40
                   CALL CURVE(XPLOT, Y2PLOT, NPTS, 0)
41
42
                   CALL DASH
43
                   CALL CURVE(XPLOT, Y3PLOT, NPTS, 0)
                   CALL RESET('DASH')
44
                   CALL STRTPT(XLNG-2.0, YLNG)
45
46
                   CALL CONNPT(XLNG-0.9, YLNG)
                   CALL MESSAG( ' EZUMAG', 16, XLNG-2.0, YLNG)
CALL MESSAG('---- EZPMAG', 16, XLNG-2.0, YLNG-0.3)
47
48
                   CALL MESSAG(10,80,0.0,-0.8)
                   CALL MESSAG(LABEL, 36, 0.0, -1.0)
CALL MESSAG('FREQ = ',7,0.0,-1.2)
50
51
                   CALL REALNO( FREQ.3.0.7,-1.2)
                   IF(IFLAG .EQ. 1) CALL MESSAG('DMIN = '.6,2.0,-1.2)
IF(IFLAG .EQ. 1) CALL REALNO( DMIN,1,2.7,-1.2)
53
```

```
SUBROUTINE CBESUY(Z,K,BJ,BY,KIND,NPRINT)
               IMPLICIT COMPLEX (A-H, 0-Z)
REAL DGMSUM, DG1, DG2, PI/3.14159265358979E0/,RRT,
2
3
               REAL
4
        C THIS SUBROUTINE CALCULATES BESSEL FUNCTIONS OF THE FIRST KIND(UN) AND
        C OF THE SECOND KIND (YN). N IS THE ORDER AND IS ALLOWED TO BE ANY
        C POSITIVE INTEGER.
8
        C THE ARGUMENT MUST BE DECLARED COMPLEX
                                                       IN THE CALLING ROUTINE.
9
        C IF A REAL ARGUMENT IS DESIRED JUST SET THE IMAGINARY PART TO ZERO.
10
11
        C FOR THE ARGUMENT Z*RHO*C EXP(I*PHI) THE EMPLOYED EQUATIONS ARE VALID
12
        C AS FOLLOWS:
               IF 0<RHO<13 THEN PHI=ANY VALUE
13
               IF RHO=13 OR 13<RHO<INFINITY THEN PHI=PI OR -PI<PHI<PI
15
        C FOR RHO=0 JO AND J1 ARE SET TO THEIR CORRECT VALUES.
16
        C HOWEVER, YO AND YI ARE NOT CALCULATED SINCE THEY APPROACH INFINITY
17
        C IN THE REAL AND/OR IMAGINARY PART, THEREFORE AN ERROR MESSAGE IS
18
19
        C PRINTED.
20
21
        C Z IS THE APGUMENT. C K IS THE ORDER.
22
23
        C BJ IS THE BESSEL FUNCTION OF THE FIRST KIND. C BY IS THE BESSEL FUNCTION OF THE SECOND KIND.
24
25
        C KIND=1 CAUSES CALCULATION OF THE BESSEL FUNCTION OF THE FIRST KIND
26
27
        C ONLY .
        C ANY OTHER VALUE OF KIND CAUSES CALCULATIONS TO BE DONE FOR BESSEL
        C FUNCTIONS OFF BOTH THE FIRST AND SECOND KIND.
29
        C NPRINT=0 CAUSES NO DEBUG PRINTOUT.
30
        C NPRINT=1 CAUSES DEBUG PRINTOUT.
31
32
33
        C THE CALLING STATEMENT MUST HAVE DECLARED THE PARAMETERS CORRESPONDING
34
           TO Z, BJ, AND BY AS COMPLEX
35
36
37
               IF(C ABS(Z) .NE. O.EO) GO TO 7
38
               BJ=(0.0E0,0.0E0)
39
               IF(K .EQ. 0) BJ=(1.0E0,0.0E0)
40
               IF(KIND .NE. 1 .AND. K .EQ. 0) PRINT 400
41
          400 FORMAT(1HO, '+++ Y NOT CALCULATED FOR ARGUMENT OF MAGNITUDE 0'//)
42
               RETURN
43
             7 IF(C ABS(Z) .LT. 13.E0) GO TO 10
44
45
        C ASSYMPTOTIC EXPANSION
46
47
48
               RH0=8.+Z
49
               MU=4*K**2
50
               RT=C SQRT(2./(PI+Z))
51
               RRT=RT
52
               IF(RRT .LT. O.) RT=-RT
               P=0.
53
        C DO LOOP FOR CALCULATING P
```

```
DO 1 N=1,30
 56
                  M=N-1
                  MM=2+M
 57
 58
                   IF(N .EQ. 1) GO TO 2
 59
                  TERM=(-1)*(MU-(2*MM-3)**2)*(MU-(2*MM-1)**2)/(MM*(MM-1)*RHQ**2)*
 60
             IF(NPRINT .EQ. 1) PRINT 100, TERM
100 FORMAT(1X, 'TERM=', 2E30.15)
 61
 62
63
                  P=P+TERM
                  IF(C ABS(TERM) .GE. C ABS(TERMS) .OR. C ABS(TERM) .LE. 1.E-17) GO
 64
 65
                 $TO 3
                   TERMS=TERM
 67
                   GO TO 1
 68
                2 TERM=1.E0
 69
                   P=TERM
                   IF(NPRINT .EQ. 1) PRINT 100, TERM TERMS=TERM
 70
 71
 72
                1 CONTINUE
 73
                3 CONTINUE
             IF(NPRINT .EQ. 1) PRINT 200,P
200 FORMAT(1H0,'P=',2E30.15)
 74
 75
 76
                   Q=0.
 77
           C DO LOOP FOR CALCULATING Q
 78
                   DO 4 N=1,30
 79
                   M=N-1
                   MM=2*M
 80
 81
                  MMM=2+M+1
                   IF(N .EQ. 1) GO TO 5
 83
                   TERM=(-1)*(MU-(2*MM-1)**2)*(MU-(2*MM+1)**2)/(MMM+(MMM-1)*RHO**2)*
 84
                 STERM
 85
                   IF(NPRINT .EQ. 1) PRINT 100, TERM
 86
                   Q=Q+TERM
                   IF(C ABS(TERM) .GE. C ABS(TERMS) .OR. C ABS(TERM) .LE. 1.E-17) GO
 87
 88
                 $TO 6
 89
                   TERMS=TERM
 90
                   GO TO 4
                5 TERM=(MU-1)/RHO
 91
                   O=TERM
 92
                  1F(NPRINT .EQ. 1) PRINT 100, TERM TERMS=TERM
 93
 94
 95
                4 CONTINUE
 96
                6 CONTINUE
             IF(NPRINT .EQ. 1) PRINT 390,Q

300 FORMAT(1H0,'Q=',2E30.15)

BJ=RT+C COS(Z-K+PI/2.-PI/4.)+P-RT+C SIN(Z-K+PI/2.-PI/4.)+Q

IF(KIND .EQ. 1) GD TO 8

DEC. SIN(Z-K-PI/2.-PI/4.)+DIRECTOR(Z-K-PI/2.-PI/4.)+Q
 97
 98
 99
100
                   BY=RT+C SIN(Z-K+PI/2.-PI/4.)+P+RT+C COS(Z-K+PI/2.-PI/4.)+Q
101
102
                8 RETURN
103
104
           C POWER SERIES EXPANSION
105
106
               10 NTERMS=35
107
108
                   KFAC=1
                   IF(K .LE. 1) GO TO 30 DO 20 N=2,K
109
110
111
               20 KFAC=KFAC+N
```

```
112
             30 TERM=(Z/2.)**K/KFAC
113
                BJ=TERM
                IF(KIND .EQ. 1) GO TO 91
114
                DG1=0.
115
                DG2=0.
116
                IF(K .EQ. 0) GO TO 80
117
                DD 60 N=1,K
118
119
             60 DG2=DG2+1./N
120
             80 TSUM3=-TERM+DG2
121
                SUMT3=TSUM3
             91 DO 40 M=1,NTERMS
122
                TERM=TERM*(Z/2.)**2*(-1)/((K+M)*M)
123
                BJ=BJ+TERM
124
                IF(KIND .EQ. 1) GO TO 92
DG1=DG1+1.EO/M
125
126
                DG2=DG2+1.E0/(M+K)
127
                DGMSUM=DG1+DG2
128
                TSUM3=-TERM+DGMSUM
129
                SUMT3=SUMT3+TSUM3
130
             92 IF(C ABS(TERM) .LE. 1.E-17) GO TO 50
131
132
             40 CONTINUE
             50 IF(KIND .EQ. 1) GG TO 93
133
                TERM3=SUMT3/PI
134
                TERM1 = (2./PI) * BJ * (EULER+C LOG(Z/2.))
135
                SUMT2=(0.,0.)
136
                IF(K .EQ. 0) GO TO 120
KM1FAC=KFAC/K
137
138
139
                TSUM2=KM1FAC+(Z/2.)++(-K)
140
                SUMT2=TSUM2
                 IF(K .EQ. 1) GO TO 120
141
                KM1=K-1
142
                DO 130 M=1,KM1
143
                KMM=K-M
144
                 TSUM2=TSUM2/(KMM+M)+(Z/2.)++2
145
146
            130 SUMT2=SUMT2+TSUM2
147
            120 TERM2=-SUMT2/PI
                BY=TERM1+TERM2+TERM3
148
             93 RETURN
149
150
                 END
```

```
SUBROUTINE CLIN EQ (A.B.X.IROW,Q.N.NDIM, IFLAG, ERR)
                 CLIN EQ USES L-U DECOMPOSITION TO FIND THE TRIANGULAR MATRICES L. U
                 SUCH THAT L + U = A. L AND U ARE
STORED IN A. THIS FORM IS USED WITH
5
6
7
                 BACK-SUBSTITUTION TO FIND THE SOLN
 8
                           A + X = L + U + X = B.
           00000
                 X OF
                 N IS THE NUMBER OF EQUATIONS AND
 9
                 N DIM IS THE DIMENSION OF ALL ARRAYS
10
                 IN THE PARAMETER LIST.
11
12
            C
                  IF IFLAG = 0. L, U, AND X ARE
13
                  COMPUTED.
14
            C
                  IF IFLAG IS NON-ZERO, IT IS ASSUMED
15
                  THAT L AND U HAVE BEEN COMPUTED IN
           000000
16
                 A PREVIOUS CALL AND ARE STILL STORED IN A. THUS ONLY X IS COMPUTED. ERR IS THE ESTIMATED RELATIVE ERROR OF THE SOLUTION VECTOR.
17
18
19
20
21
22
                     COMPLEX
                                       A, B, X, T
23
24
25
                     REAL ERR
                     DIMENSION A(NDIM,NDIM),B(NDIM),X(NDIM)
DIMENSION IROW(NDIM),Q(NDIM)
                     DATA EPS /1.0E-15/
26
27
28
                     IF (N.GT.NDIM) GO TO 900
29
30
                     IF (IFLAG.NE.O) GO TO 600
                     DO 050 I = 1,N
31
               Q(I) = 0.0

DO 040 J = 1,N

QQ = C ABS (A(I,J))

040 IF (Q(I).LT.QQ) Q(I) = QQ

IF (Q(I).EQ.0.0) GO TO 901
32
33
34
35
36
37
               050 CONTINUE
                     ERR = EPS
38
               PPIV = 0.0
DO 100 I = 1,N
100 IROW(I) = I
39
40
41
42
43
                     DO 500 L = 1,N
                      PIVOT = 0.0
44
                     K = L - 1
DO 240 I = L,N
45
46
               IF (K.LT.1) GO TG 230

DO 220 J = 1,K

220 A(I,L) = A(I,L) - A(J,L) * A(I,J)

230 F = C ABS (A(I,L)) / Q(I)

IF (PIVOT.GT.F) GO TO 240
47
48
49
50
51
52
                      PIVOT = F
 53
                      NPIVOT = I
                240 CONTINUE
```

```
IF (PIVOT.EQ.O.O) GO TO 901

IF (PPIV.LE.PIVOT) GO TO 250

ERR = ERR + PPIV / PIVOT

IF (ERR.GE.1.0) GO TO 901
 55
 56
 57
 58
               250 PPIV = PIVOT
 59
                     IF (NPIVOT.EQ.L) GO TO 280
 60
 61
                     Q(NPIVOT) = Q(L)
 62
                     J = IROW(L)
 63
                     IROW(L) = IROW(NPIVOT)
 64
                     IROW(NPIVOT) = J
 65
                     DO 260 I = 1,N
 66
                     T = A(L, I)
 67
                     A(L,I) = A(NPIVOT,I)
                     A(NPIVOT,I) = T
 68
               260 CONTINUE
 69
               280 IF (L.EQ.N) GD TO 500
T = (1.0E0,0.0E0) / A(L,L)
 70
71
72
73
74
75
                    K = L + 1
M = L - 1
               DO 450 I = K,N

IF (M.LT.1) GO TO 400

DO 350 J = 1,M

350 A(L,I) = A(L,I) ~ A(L,J) + A(J,I)
 76
77
 78
               400 \ A(L,I) = T + A(L,I)
 79
               450 CONTINUE
 80
               500 CONTINUE
 81
                     IF (ERR.GT.1.0E-5) PRINT 998, ERR
 82
 63
               600 DO 620 I = 2,N
620 X(I) = (0.0E0,0.0E0)
U = IROW(1)
 84
 85
 86
                    X(1) = B(J) / A(1,1)
DO 700 I = 2,N
 87
 88
                    J = IROW(1)
K = I - 1
 89
 90
               DO 650 L = 1,K
650 X(I) = X(I) + A(I,L) + X(L)
 91
 92
 93
                     X(I) = (B(J) - X(I)) / A(I,I)
 94
               700 CONTINUE
 95
                     K = N - 1
                    DO 800 I = 1,K
J = N - I
 96
 97
 98
                     M = J + 1
                     DO 800 L = M,N
 99
               X(J) = X(J) - X(L) + A(J,L)
800 CONTINUE
100
101
102
                     RETURN
103
               900 PRINT 999
104
                     ERR = 1.0
105
                     RETURN
106
107
               901 PRINT 997
108
                     ERR = 1.0
                     RETURN
109
               997 FORMAT ('1ERROR IN CLIN EQ, MATRIX IS SINGULAR')
998 FORMAT (' CAUTION-',
110
111
```

112 \$ 'CLIN EQ HAS DECOMPOSED AN ILL-CONDITIONED MATRIX.',/,
113 \$ 'RESULTS WILL HAVE RELATIVE ERROR =',E11.2)
114 999 FORMAT ('1ERROR IN CLIN EQ, MATRIX SIZE GREATER THAN NDIM')
115 END

```
1 FUNCTION C ANG(ARG)
2 IMPLICIT REAL (A-H.O-Z)
3 COMPLEX ARG,MINUSI/(0.0E0,-1.0E0)/
4 ARGR=ARG
5 ARGI=MINUSI+ARG
6 C ANG= ATAN2(ARGI,ARGR)
7 IF(ARGI .LT. 0.) C ANG=C ANG+6.2831853072E00
8 RETURN
9 END
```

```
COMPLEX FUNCTION CAPA(SP,RHO)
IMPLICIT COMPLEX (A-H,O-Z)
COMPLEX IM/(0.E0.1.E0)/,J1,J2
3 4 5 6 7 8 9 10 11
                     COMPLEX KSO
                    COMMON/ONE/H12,H22,J1,J2,S0,ARG0,KA,KS0
DEFINE CAPG1(ARG) = SQRT(ARG/(6371.0E0+ SIN(ARG/6371.0E0)))
ARGP = KA+SP
                     TERM1 = (0.0E0,0.785398163397448E0)*((SP/S0)**2-1.0E0)
TERM2 = 2.0E0*ARG0*(1.0E0-.25E0*ARGP**2)
                     IF(RHO .EQ. 0.0) THEN
12
13
14
15
16
                                                CAPA = (SP/SO) ** 4+ TERM1 * (TERM2 * H12 + ARGP * + 2 + H22)
                                          ELSE
                                                COFAMN = TERM1+(TERM2+J1+ARGP++2+J2)
                                                 ARGU = KSO+RHO
                                                 CALL CBESJY(ARGU, 0, BJ, BY, 0)
                                                HO2 = BJ-IM+BY
18
                                                CAPA = COFAMN+H02+CAPG1(RHO)
                     END IF
20
21
                     RETURN
                     END
```

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